

N3 IMU RTK GNSS Receiver

User Guide



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Trademark notice

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FCC Notice

SinoGNSS® N3 GNSS receivers comply with the limits for a Class B digital device, pursuant to the Part 15 of the FCC rules when it is used in the Portable Mode.

Operation is subject to the following two conditions:

- (1) This device may not cause harmful interference;
- (2) It must accept any interference received, including interference that may cause undesired operation.

Copyright Notice

This is the V1.0 (July, 2021) revision of the N3 GNSS Receiver User Guide. It cannot be copied or translated into any language without the written permission of ComNav Technology.

Technical Assistance

If you have any question and can't find the answer in this manual, please contact your local dealer from which you purchased the N3 receiver. Alternatively, request technical support from ComNav Technology Website: www.comnavtech.com or technical support email: support@comnavtech.com. Your feedback about this Guide will help us to improve it with future revisions.

Safety Information

Before using the receiver, please make sure that you have read and understood this User Guide, as well as the safety requirements.

- Connect your devices strictly based on this User Guide
- Install the GNSS receiver in a location that minimizes vibration and moisture
- Avoid falling to ground, or colliding with other items

- Do not rotate 7-pin Lemo port
- Do not cover the radio, keep a sound ventilation environment
- To reduce radiation, please keep above 2 meters away from the radio station
- Take lightning protection measures when installing antennas
- Change the cable if damaged

Related Regulations

The receiver contains integral Bluetooth® wireless technology and UHF. Regulations regarding the use of the datalink vary greatly from country to country. In some countries, the unit can be used without obtaining an end-user license. But in some countries the administrative permissions are required. For license information, please consult your local dealer.

Use and Care

The receiver can withstand the rough treatment that typically occurs in the field. However, the receiver is high-precision electronic equipment and should be treated with reasonable care.

Warning and Caution

An absence of specific alerts does not mean that there are no safety risks involved. A Warning or Caution information is intended to minimize the risk of personal injury and/or damage to the equipment.

WARNING- A Warning alerts you to a potential risk of serious injury to your person and/or damage to the equipment, because of improper operations or wrong settings of the equipment.

CAUTION- A Caution alerts you to a possible risk of damage to the equipment and/or data loss.

Warranty Notice

ComNav Technology does not warranty devices damage because of force majeure (lighting, high voltage or collision).

ComNav Technology does not warranty the disassembled devices.

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1 Introduction

The SinoGNSS® N3 GNSS Receiver User Guide is aimed to help you get familiar with the N3 receiver and start your project effectively. We highly recommend you to read this manual before surveying, even you have used other Global Positioning System (GPS) receivers before.

1.1 About the receiver

With SinoGNSS® Quantum™ algorithm, N3 GNSS receiver can be applied in RTK mode with all GNSS constellations. N3 receiver has ultra-small size and strong anti-interference ability to make it possible to work even in harsh environments. It is the ideal RTK/GNSS product for surveyors.

1.2 Receiver features

The SinoGNSS® N3 GNSS Receiver keyfeatures:

- Ultra small and super light
 - Size (W × H): 15.5cm × 7.3cm
 - Weight: 1.2kg (including 2 batteries)
- 1198 channels of simultaneously tracked satellite signals
- Increased measurement traceability with SinoGNSS® Quantum™ algorithm technology
- Hot swap battery design
- Cable-free Bluetooth wireless technology
- 5 indicator LEDs for battery, diff, satellite, WIFI/GPRS and 2 function buttons for power and static
- IP67 waterproof
- Full base/rover interoperability
- Integrated receiving & transmitting radio with 12.5KHz frequency interval
- Integrated IMU sensor
- Integrated WiFi module
- Long distance range radio module
- Integrated 4G module, support Ntrip and Point to Point/Points protocols
- Support long baseline E-RTK™ (Beidou B3 signal is included in RTK calculate engine)

1.3 N3 Receiver parts list

This section provides overall N3 receiver parts list, including basic supplies and customized kits based on your requirements.

1.3.1 Basic Supply kit

SinoGNSS® N3 GNSS Receiver Basic Supply kit contains two receivers and related accessories.

Item	Picture
2* Kits N3 Receivers	
1*GNSS Connector	
2*7-pin Lemo to RS232 Cable	
2* 7-pin Lemo to USB Cable	
External Power Cable	
2* Whip Antenna (UHF)	
1*2m-Range Pole with yellow bag	

4* Lithium-ion Battery	
2* Battery Charger	
R550 Controller	
Controller Battery, Charger and Cable	
Controller Bracket	

Optional accessories:

Double Bubbles Tribrach with High Adapter	
1* 30cm Extension bar	

1.3.2 Optional Datalink kit

This kit is necessary for long distance radio communication, shown in the following figures:

Item	Picture
External Radio CDL7	 A black, rectangular external radio with a textured surface and a small display screen on the front.
2-pin Lemo Power Cable	 A black cable with a red Lemo connector on one end and a standard power plug on the other.
7-pin Lemo Data Cable	 A black cable with a blue Lemo connector on one end and a standard data connector on the other.
N-Type to TNC Convertor	 A small, cylindrical metal connector with an N-type female connector on one end and a TNC male connector on the other.
N-type to N-type Antenna Cable	 A black cable with N-type connectors on both ends.
N-Type Radio Antenna	 A black cable with an N-type connector on one end and a long, thin antenna element on the other.

1.3.3 Transport Cases

Standard transport case is designed for containing basic supply kit of one SinoGNSS® N3 GNSS Receiver.



Base



Rover

The optional choice is provided to have capacity of two kits of N3 receivers.



2 Setting up the receiver

This chapter provides general information on environmental requirements, setup, power supply and connection of the N3 receiver.

2.1 Environmental requirements

To keep the receiver with a reliable performance, it is better to use the receiver in safe environmental conditions:

- Operating temperature: -40°C to +65°C
- Storage temperature: -40°C to +85°C
- Out of corrosive fluids and gases
- With a clear view of sky

2.2 Front panel

Receiver front panel contains 5 indicator LEDs, Power button and Record button. The indicator LEDs show the status of differential, satellite tracking, WIFI/GPRS and battery. For detailed information, see [chapter 3.3](#).



2.3 Lower housing

Receiver lower housing contains a serial port, UHF radio antenna connector, two removable battery compartments (the SIM card slot is located in compartment A), and a threaded insert.



2.4 Power supply

N3 GNSS receiver supports internal batteries and external power input.

2.4.1 Internal batteries

The receiver is equipped with two rechargeable Lithium-ion batteries, which can be removed for charging. The N3 receiver adopts the hot swap battery design that provides you an effective survey workflow. The internal batteries typically provide about 25-hour operating time as a rover, about 19-hour operating time if operated as a base station with internal UHF Tx (transmit at 1-2 watts). However, this operating time varies based on environmental conditions.

- **Battery Safety**

Charge and use the battery only in strict accordance with the instructions below:

- Do not use or charge the battery if it appears to be damaged. Signs of damage include, but are not limited to, discoloration, warping, and leaking battery fluid.
- Do not expose the battery to fire, high temperature, or direct sunlight.
- Do not immerse the battery in water.
- Do not use or store the battery inside a vehicle during hot weather.
- Do not drop or puncture the battery.
- Do not open the battery or short-circuit its contacts.

- **Charging the Lithium-ion Battery**

Although a dual battery charge is provided, the lithium-ion battery is supplied partially charged. To charge the battery, first remove the battery from the receiver, and then place it in the battery charger, which is connected to AC power. Please obey the following instructions when charging your batteries:

- Charge the battery completely before using it for the first time.
- Fully charge takes approximately 6 hours per battery at room temperature.
- If the battery has been stored for a long time, charge it before your field work.
- Re-charge the battery at least every three months if it is to be stored for long time.

- **Storage of the Lithium-ion Battery**

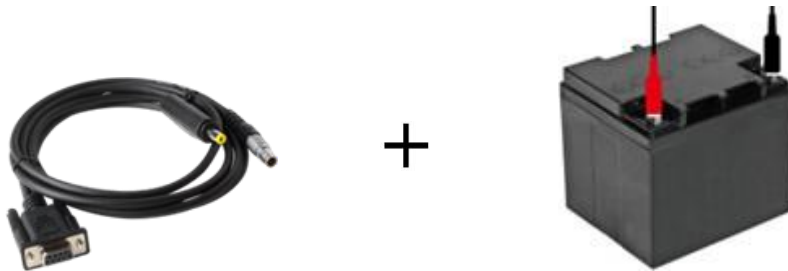
- Do not keep batteries inside the receiver if the receiver not used for long time.
- Keep batteries in dry conditions.
- Take out the batteries from receiver for shipment.

- Dispose of the Lithium-ion Battery
 - Discharge a Lithium-ion battery before dispose of it.
 - Dispose of batteries is an environmentally sensitive manner, and adhere to any local and national regulations concerning battery disposing or recycling.

WARNING – Do not damage the rechargeable Lithium-ion battery. A damaged battery can cause an explosion or fire, and can result in personal injury and/or property damage.

2.4.2 External Power Supply

The receiver is connected to an external power supply through a lemo to RS232 cable, and make sure that the red alligator clip is connected to the positive of external power supply, black one to negative. Over-voltage function cannot protect your N3 receiver if reverse connection.

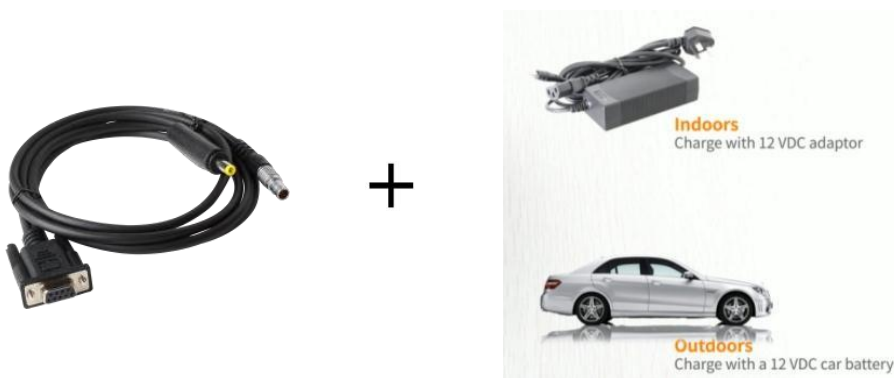


Tip: The power consumption will be increasing if the base station transmits correction data through internal UHF in the RTK mode; therefore, we strongly suggest using external power (7-28 volt DC) for the base station.

2.4.3 Charge Battery via N3 Receiver

N3 GNSS Receiver can work as a charger, it means you can charge batteries directly if the charger not by your side.

1. Power off N3 receiver with batteries inside;
2. Connect N3 receiver to 12V external power with serial cable;
3. Receiver will charge the battery from Side B to Side A, the red power led will flashing during charging and will off when battery full.



2.5 Pole-mounted setup

To mount the receiver on a range pole as the figure shown below:



- Thread the receiver onto the range pole
- Mount the controller bracket to the pole
- Install the controller into the bracket

Tip: Do not tightly clamp the controller on the Range Pole.

3 General Operation

This chapter introduces all controls for the general operation, including button functions and all LED behaviors on the front panel.

3.1 Button functions

There are two buttons on the front panel, power button and record button.

- Power button:

Press the power button for about 1 second to turn on the receiver;

To turn off the receiver, long press the button for 3-4 seconds until all LEDs off.

- Record button:

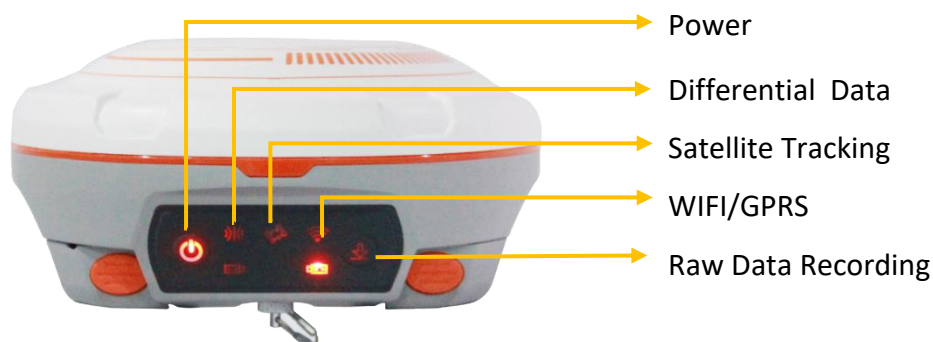
Switch to static mode: Long press the record button for about 2 seconds, release immediately when hearing beep from receiver;

Switch to RTK mode: press the button until Raw Data recording LED off.

Tip: The record button only works when receiving satellite signals, otherwise it will show timeout.

3.2 LED behavior

The LEDs on the front panel indicate receiver working status. Generally, a lit or slowly flashing indicates normal operation, and an unlit LED indicates that no operation is occurring. The following figure and table define each possible LED state:



LEDs	States	Description
Power	Lit	Enough power
	Flashing	Low power
Differential Data	Flashes once per second	Receiving/transmitting differential data
Satellite Tracking	Fast flashing/ Flashes 1 time every 5 seconds	No satellite received
	Flashes N times every 5 seconds	Received N satellite signals
Internal 4G and WIFI	Flashes once per second	GPRS function is working
	Flashes once per five- second	WIFI is working
	Flashes according to the selected sample interval	1) Sample interval varies from 20Hz to 60s. 2) Flashing 1/s simultaneously with differential light if internal memory is run off

Power LEDs:

Power supply: 1) Two power LEDs are on if using the external power supply; 2) Only power LED of working battery will be on if using the internal battery.

Low battery: 1) Power LED will flash with beep only with one battery; 2) if with two batteries, the power LED of low battery will flash, and swapped to another battery when it is run off.

3.3 Receiver Web GUI interface

Step 1: Connect Wi-Fi of N3 receiver

Turn on the N3 GNSS receiver and wait for the N3 serial number to appear under the available Wi-Fi networks on your smart phone or office computer.

For example, **N3-T0350XXXX** (where xxxx represents the last four digits of the receiver serial number).

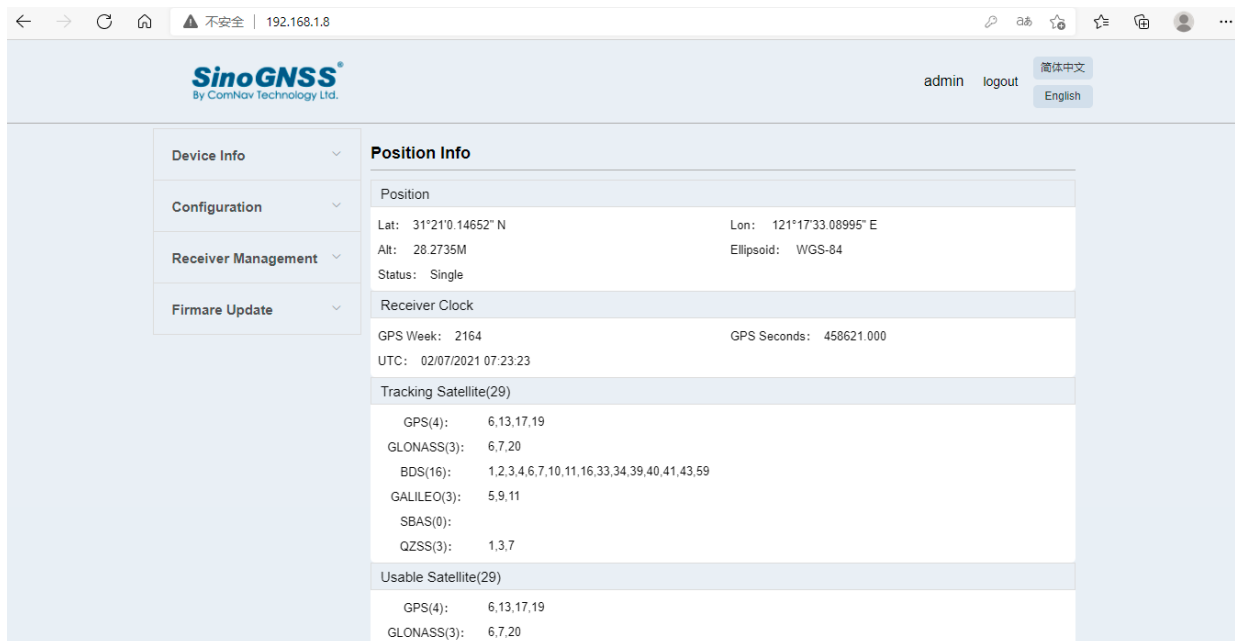
Enter password: 12345678

Step 2: Login the Web

Select the receiver, open a web browser and then enter the following IP address:

http://192.168.1.8

Tip: Most web browsers for computers / laptops and smart phones / PDAs support the receiver Web GUI

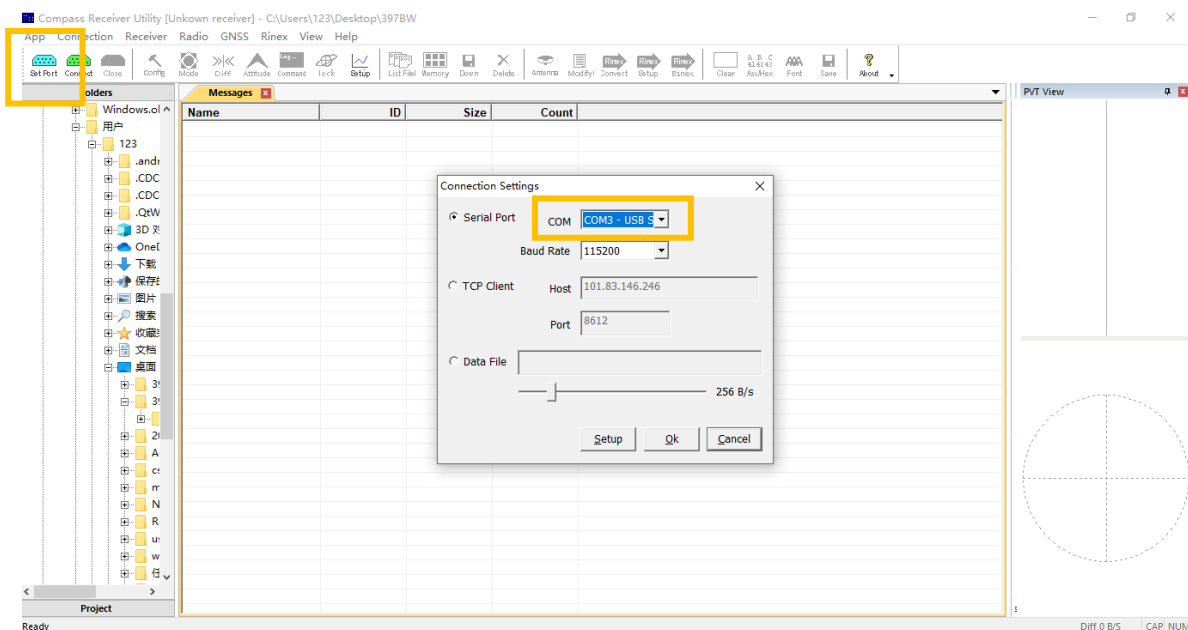


4 Static survey

This chapter describes static survey through N3 receiver and CRU software. For static survey, you cannot change settings through front panel, you can configure it via Compass Receiver Utility (CRU): 1) Receiver configuration; 2) check receiver settings and status; 3) convert data to Rinex format.

4.1 Receiver Configuration

1. Download and install CRU software from the link below (ensure the driver is properly installed in your PC):
<http://www.comnavtech.com/download.asp?bigclassid=28>
2. Connect the receiver with your PC through serial port cable.
3. Turn on your N3 receiver and click **set port** in CRU -> select proper serial port in the serial port option-> enter proper baud rate -> click **Ok** to complete receiver connection.
The SN of receiver will appear in the title bar if connected successfully.



Tips: two types of cable are provided in your package,

- 1) We recommend to use 7-pin Lemo to USB cable to download raw observation data;
- 2) With 7-pin Lemo to RS232 cable, you can connect N3 receiver with external power or firmware upgrade.

4. Click **Config** to configure the receiver:
 - **Sample Interval**: change the sample interval of observations, the maximum data rate is 20 Hz, the minimum is one observation per minute.
 - **Mask angle**: disable the receiver to track satellites that below the mask angle. You can set mask angle values for different constellations, which can reduce serious multipath influence or low SNR.

- **Data Log:** logging data manually or automatically.
- **Data Log Session:** 1) Manual means that the receiver keeps recording data in one file until the receiver is turned off or its memory runs out; 2) if set to 1\2\3\4\12 hours, the data recorded will be saved into a file every 1\2\3\4\12 hours.

Item	Parameter
Model of the receiver	2001
Receiver No.	302520
Date of manufacture	2018/03/01
Option	No
Version	H:1.12 B:5.0.1 S:3.6.8
Memory	255MB
Sample Interval(second)	5 s
GPS Mask Angle(degree)	10
BDS Mask Angle(degree)	10
GLONASS Mask Angle(degree)	10
GALILEO Mask Angle(degree)	10
Data Log	Manual
Data Log Session	Manual
Port Configuration	Normal
Work Mode	Normal
Correction Port	Port 1
Format of Correction	CMR
Register Code	16777215-42949-67295

Buttons on the right: Default Settings, Refresh Settings, Apply Settings, Register Receiver, Update Firmware, Local Log, Exit.

5. Complete all configurations and click Apply Settings to save settings. Exit and restart the receiver to activate configurations

4.2 Static Data Collection

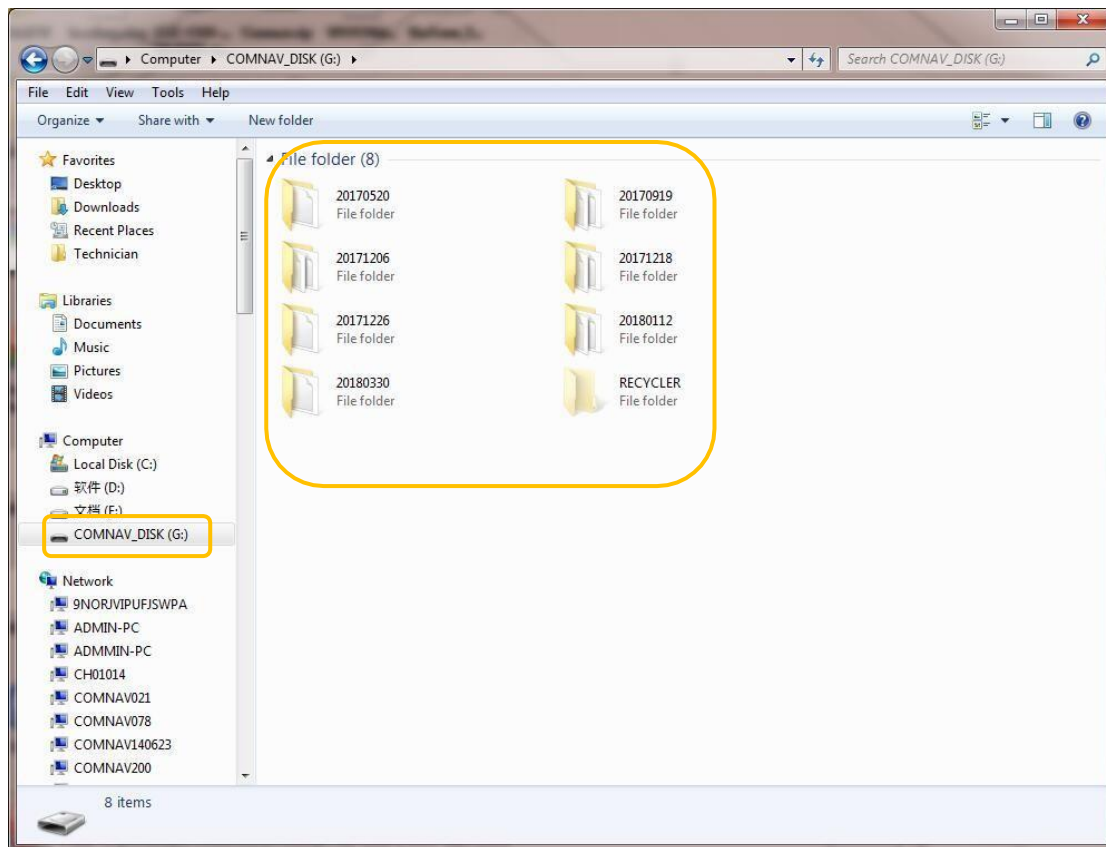
Static survey is mainly used for the control survey. To reach millimeter accuracy, follow as below:

- At least 3 GNSS receivers are required to form a stable triangulation network.
- It is better to set Data Log Session as manual on the known point.
- Power off the receiver before moving to other observation site.
- To quickly post-process static observation raw data, write down the station name, receiver SN, antenna height, start and end time for each observation site.

Tip: You can start recording static data in the front panel, it's convenient for you.

4.3 Static Data Download

The raw observation data is saved in internal memory of N3 receiver, when connected with PC via USB cable, the N3 receiver can work as a USB Flash Disk, which means you can copy or cut static data to PC directly.



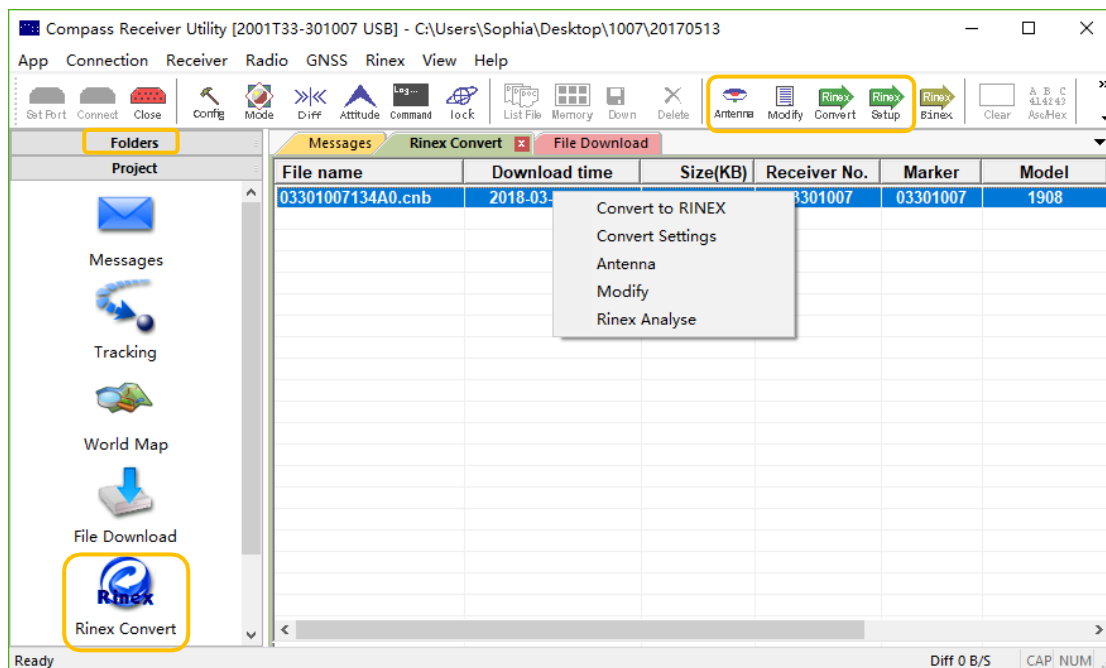
Tip1: Default memory for N3 receiver is 8GB, and 16GB, 32GB optional.

Tip2: The receiver will stop recording raw data if the internal memory runs out.

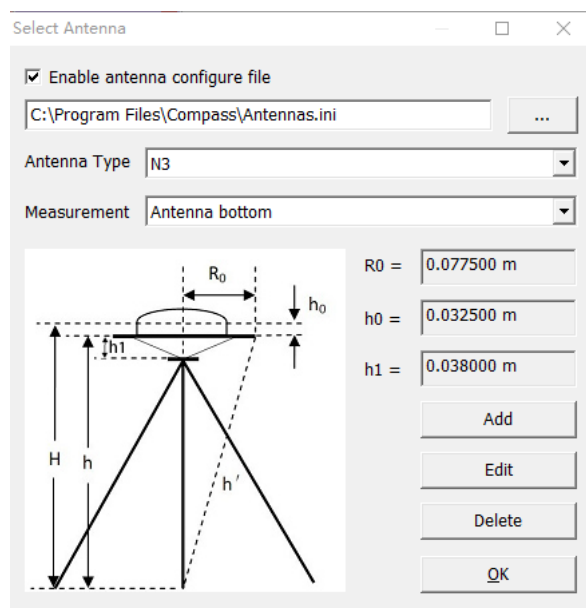
4.4 RINEX Convert

After copy raw observation data to PC, you can convert the data from ComNav binary format (*.cnb) to RINEX in CRU software.

1. Start CRU software;
2. Click **Folders** and select the path of your CNB data;
3. Click **Rinex Convert** to check all raw data on main window. Right click on the file to modify antenna, Convert Settings and Convert to RENIX, or use fast icon in standard bar.



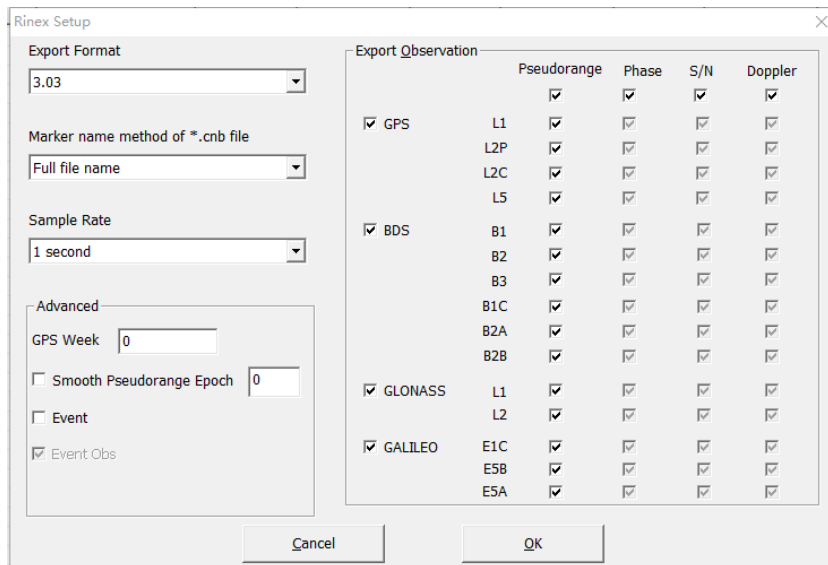
- Click  to select the **Antenna Type** and **Measurement**. If you cannot find N3 antenna, 1) input the value of R_0 (horizontal offset from measurement mark to phase center), h_0 (vertical offset from measurement mark to phase center) and h_1 (vertical offset from measurement mark to receiver bottom). R_0 is 0.0775m, h_0 is 0.0325m and h_1 is 0.038m respectively for N3 receiver; 2) or check **Enable antenna configure file** to select **Antennas.ini** file to select Antenna type again. You can also add, edit and delete antenna types based on your requirement.



- Click  to change **Convert Settings**, mainly export format and export



observation information.



Tip: In some Post Processing software, the BeiDou observations cannot be processed, you can uncheck the BeiDou B1,B2,B3 observations.

- Click  to **Convert to RINEX**, the RINEX data will be save in the same path as raw observation data.

5 Real-Time Kinematic Survey (RTK)

This chapter introduces how to conduct RTK Survey with Survey Master Software, including software installation, start a new project, receiver connection and RTK working modes (Radio, CORS and GPRS).

5.1 Installation of Survey Master

Survey Master is available on Google play, you can download for free and install the software to SinoGNSS controller R550.

Also you can download the latest version from our website:

<http://comnavtech.com/download.asp?bigclassid=28>

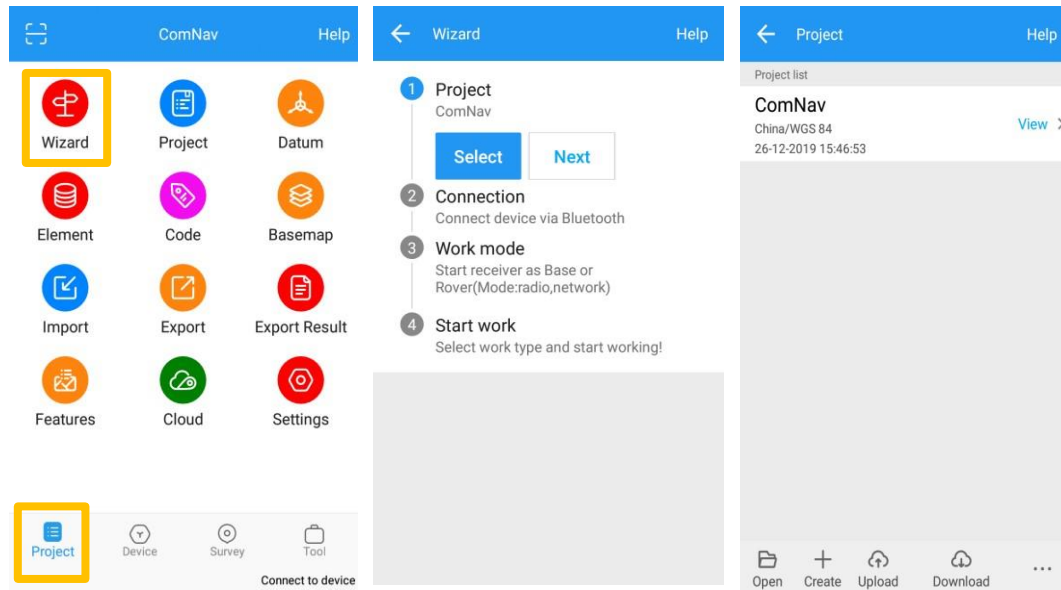
5.2 Wizard function in Survey Master

Follow the Wizard, you can quickly learn the general workflow of Survey Master, also you can quick start your survey by this function no matter you are experienced one or new user.

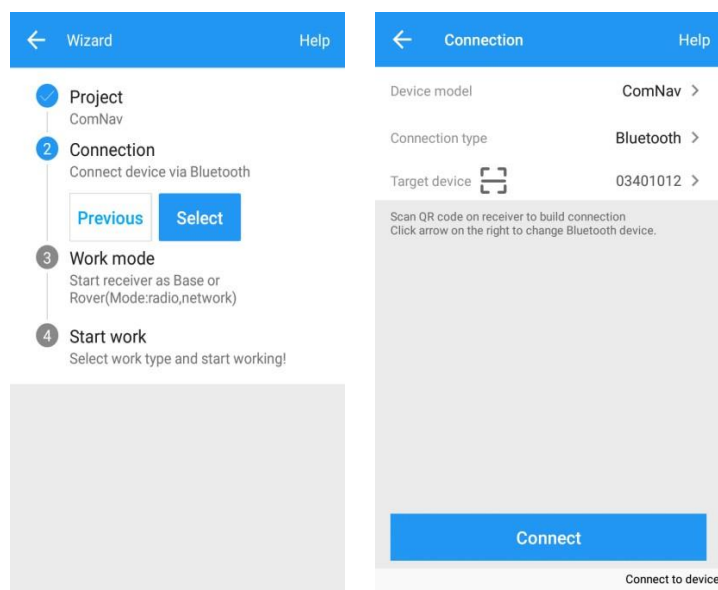
In Project menu, tap Wizard.

1. **Project**: Click **Select** to go into Project interface to create or select a project. For

detailed information, you can refer to [chapter 5.3](#).

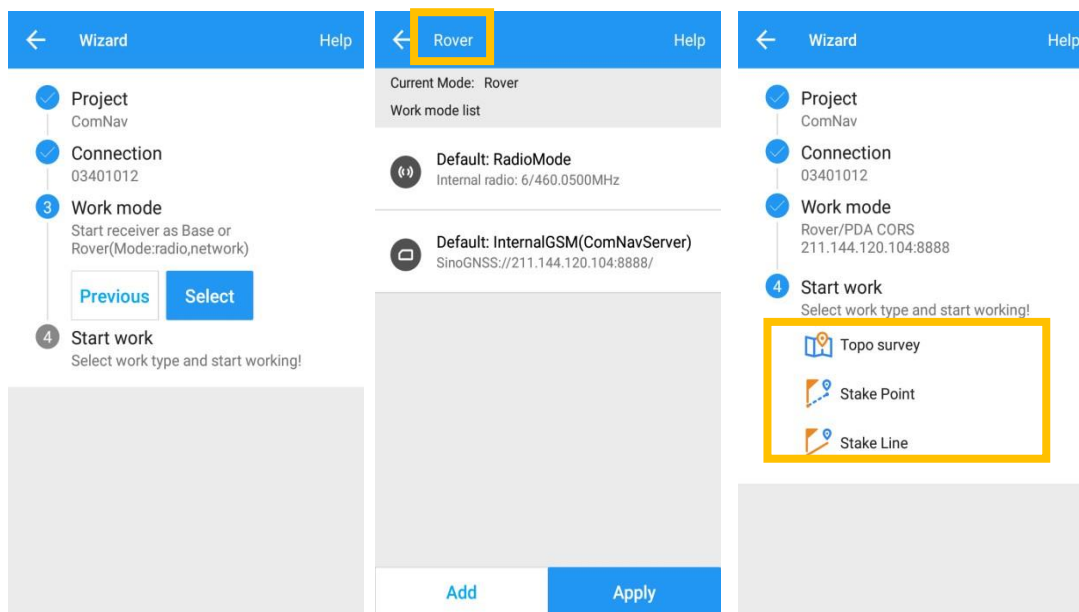


2. **Connection**: Click **Select** to go into Bluetooth connection interface. For detailed information, you can refer to [chapter 5.4](#).

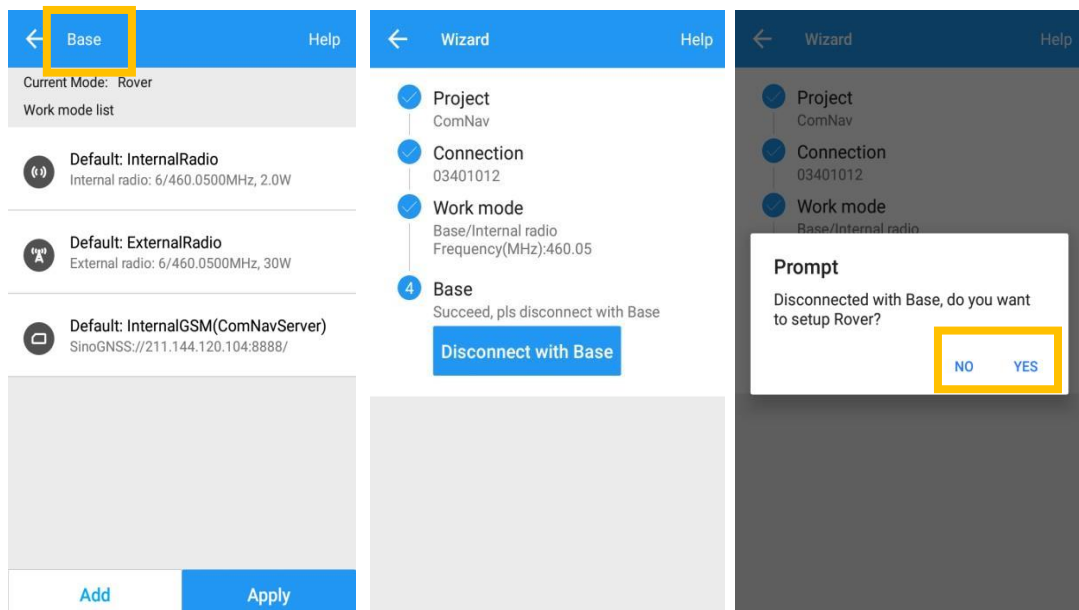


3. **Work mode**: Click **Select** to go into QuickSetup interface to start your receiver as Base/Rover. For detailed information, you can refer from [chapter 5.5](#).

If you start your receiver as Rover, then you can start work directly of topo survey or stakeout.

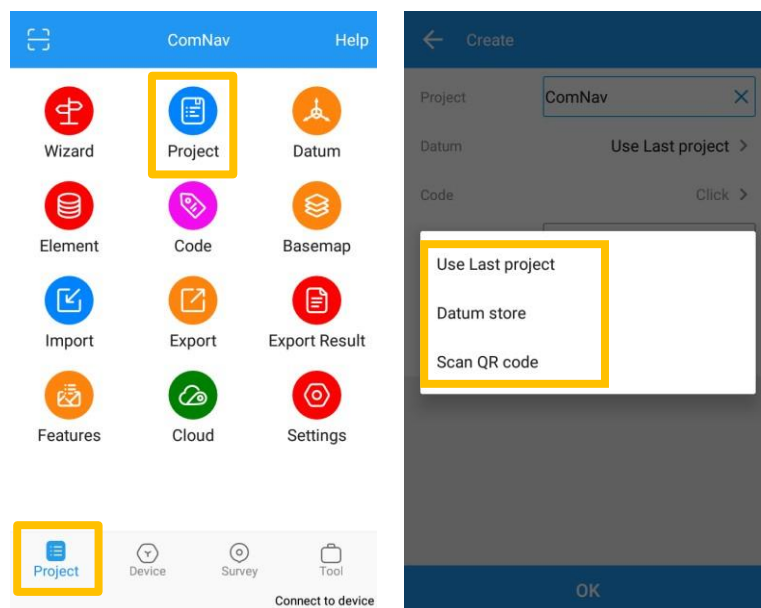


If you start your receiver as Base, after Disconnect with Base, there will be a Prompt.
 YES: will guide you to start Rover in Wizard interface;
 NO: will disconnect the base and exit Wizard.

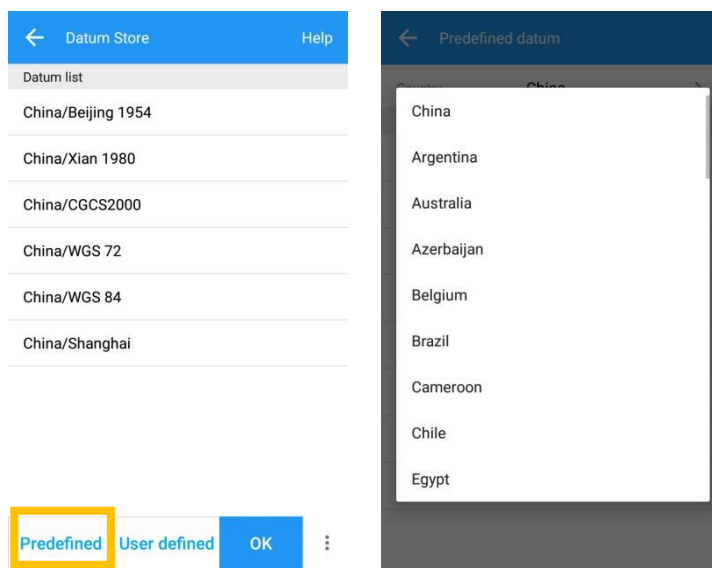


5.3 Start a New Project

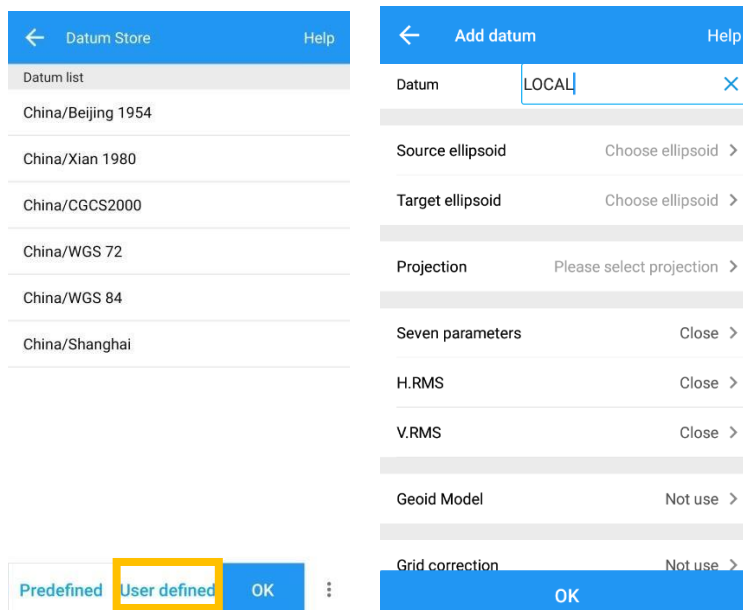
Click **Project**, you can use the same Datum with last project, choose a datum in store and scan QR code from other controller to add Datum, even sharing project with cloud.



- Select a Predefined datum: You can select datum directly from the list. Survey Master currently has 49 countries datum and will add more afterwards.



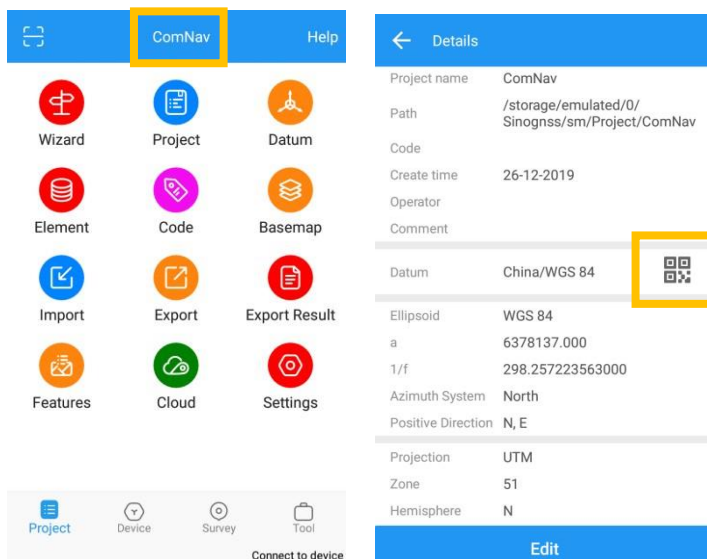
- Create a User defined datum: If you cannot find datum you want in the list, follow instructions below to add one: select Ellipsoid, Projection for your datum, and even seven parameters, geoid model based on your request.



Tip1: if asked username and password for seven parameters, enter **admin admin**

Tip2: For H.RMS and V.RMS, it will show if do **Site Calibration**.

- Share Datum via QR code.
- After you build a project, press the project name, it will generate a QR code. Users can use the Scan function in the main interface to access the coordinate system.

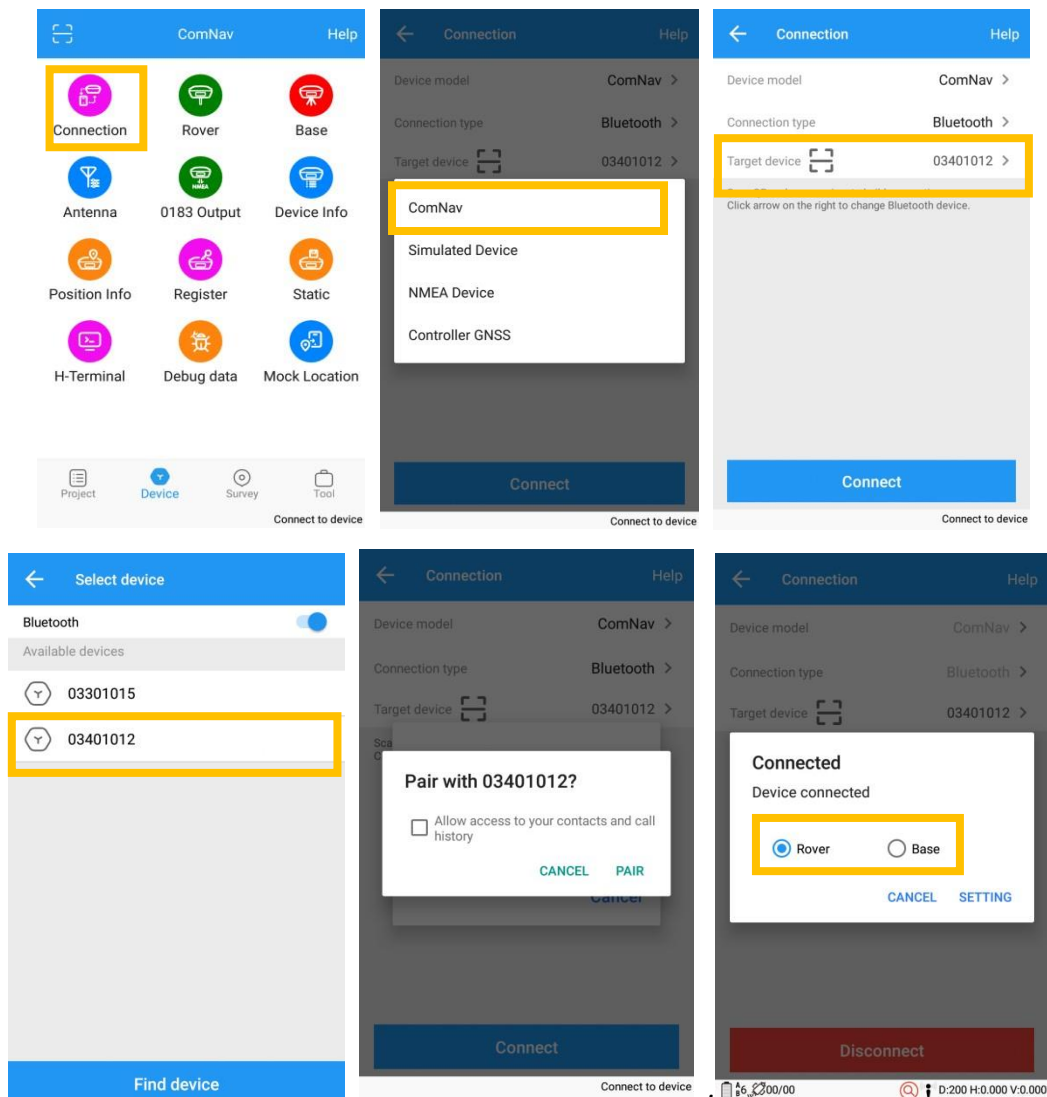


5.4 Bluetooth connection

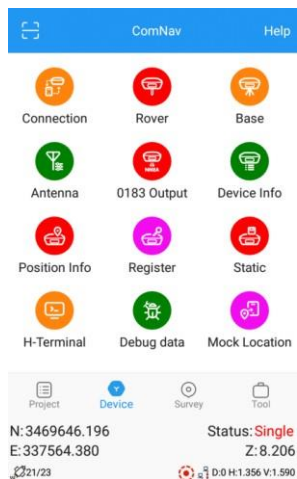
To connect Survey Master with N3, switch to **Device** interface, tap **Connection** to go into Bluetooth connection interface.

- Make sure device Bluetooth turned on;
- Click **Find device**—select SN of your N3 receiver—allow pair

After connect ComNav receiver, you can check the device version in **Device Info**.



After connected successfully, the bottom will show the positioning status.



Tip: If you are failed to connect with receiver through Survey Master, you can just follow prompt info to go into the device Bluetooth setting interface to make sure Bluetooth paired successfully. Sometimes you need restart the receiver or Survey Master Software.

5.5 Internal Radio Mode

N3 GNSS receiver supports transmit & receive the correction data in internal radio mode. To conduct the RTK survey in internal radio mode, it requires:



Tip: The external power supply is recommended when N3 set as a base station.

More: Aim to improve the radius of work field, we can change the base receiver's Whip Antenna to External Antenna. And others no need change.

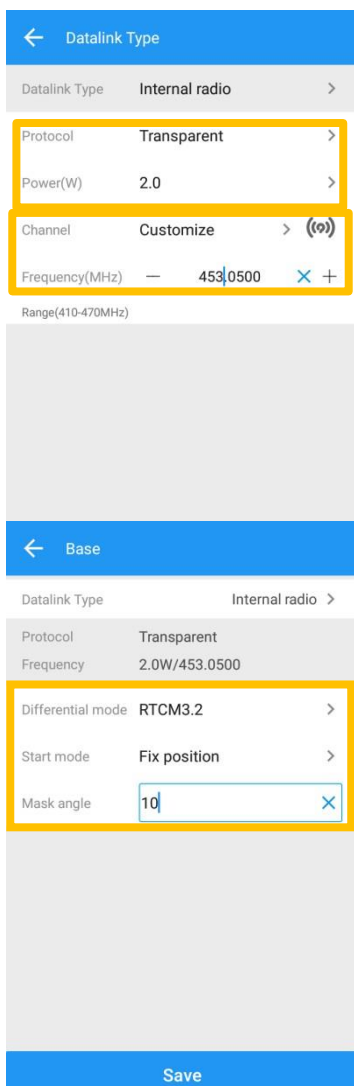
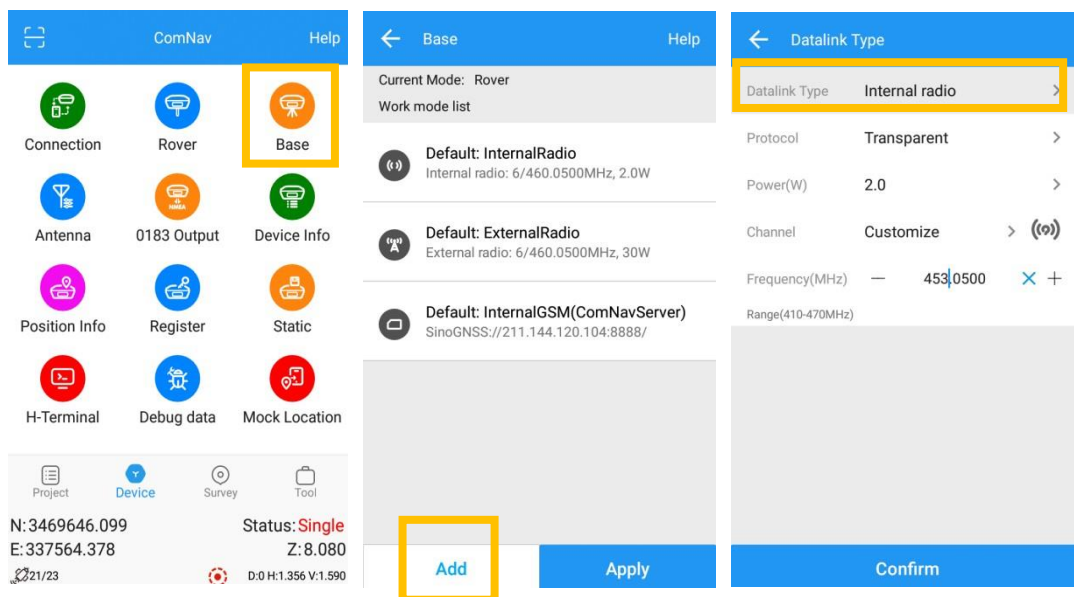


5.5.1 Start Base Station by Survey Master

Firstly, build Bluetooth connection between the N3 receiver and your controller as shown in [Chapter 5.4](#).

Secondly, modify parameters including correction format, antenna type and communication protocols:

- Click **Device**-> **Base** -> **Add**, select **Internal radio**.



- Protocol and channel: Set protocol and frequency for the base;

- Start mode: Fix position means you have a known coordinate for base, or get a point from GNSS;
- Differential mode: Support RTCM32, RTCM32(MSM5), RTD, CMR, CMR+(GPS only)

FixPosition

Base station coord... Library choose Receive

Name Base:pd

Code

Display type Local grid coordinate

N 3469655.236

E 337581.203

Z 25.088

Slant(S) 1.850

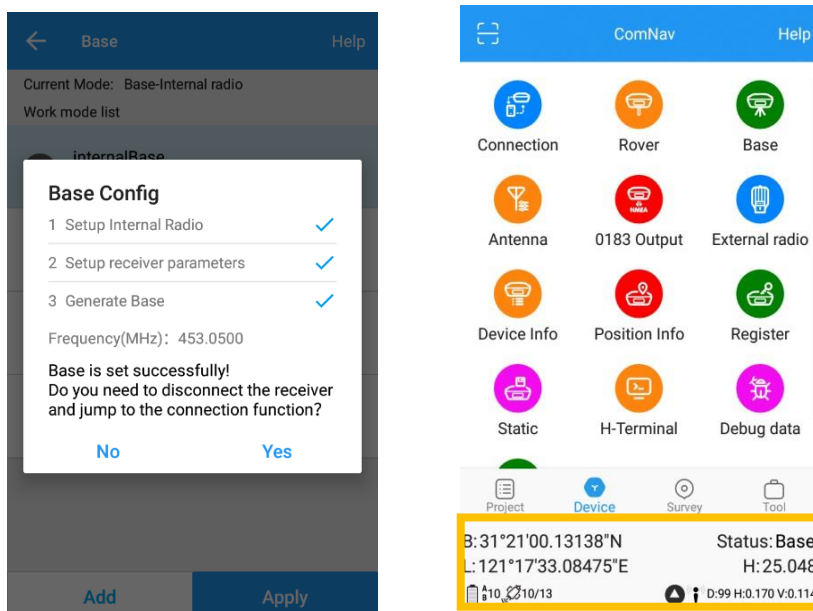
☐ Bottom of receiver(H) ☒ Slant(S)

Antenna type T30(NGS)

OK

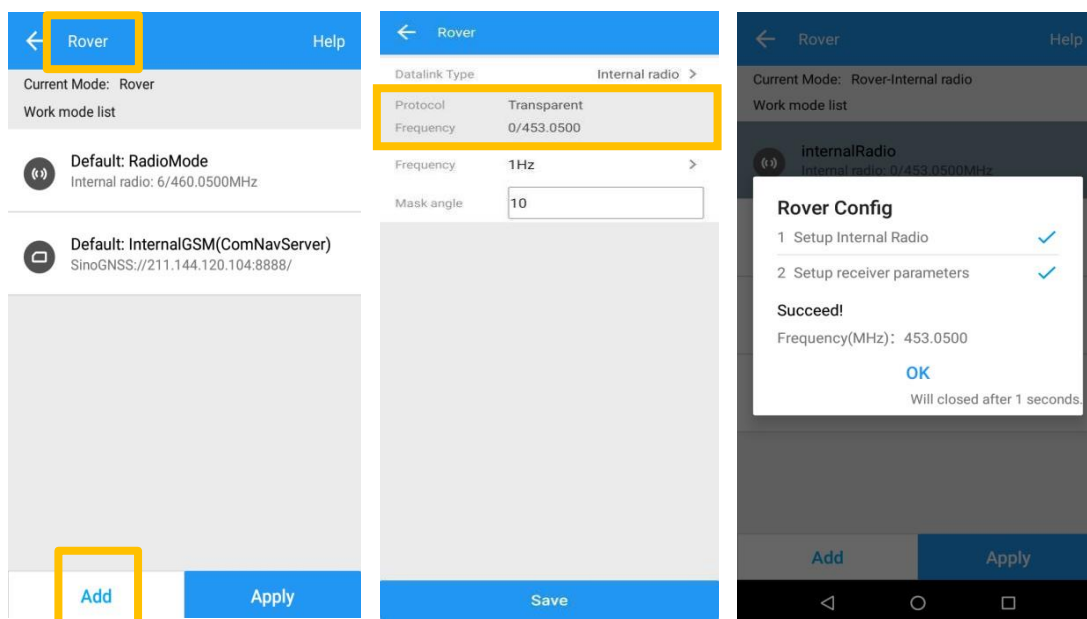
- Library choose: Choose a known point from Element;
- Receive: Receive a point from GNSS;

When start Base succeed, it will show as below in Survey Master.



5.5.2 Start Rover Station by Survey Master

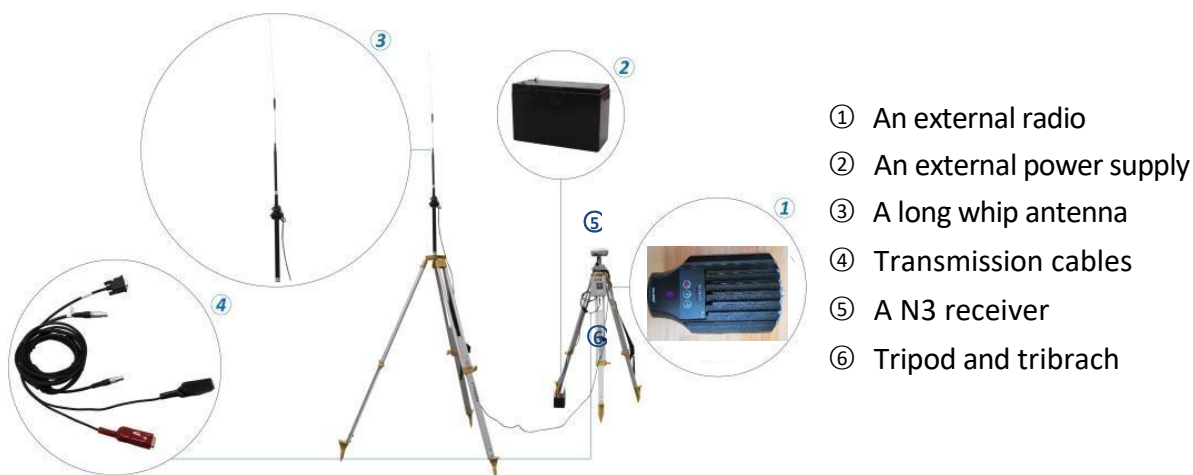
- Connect Survey Master with N3 receiver via Bluetooth based on [Chapter 5.4](#).
- Set same protocol and frequency with Base receiver.
- The current status on the bottom will change from Single to Fixed.



5.6 External radio mode

The external radio mode can extend RTK working distance, which is ideal for areas with high constructions or strong signal interference. To set up external radio mode, it requires:

- Base station



Tip: 1) See [Appendix A](#) for detailed definition of 7-pin Lemo cable that connects the N3 receiver and external radio; 2) See [Appendix B](#) for the operating information of CDL7.

*Warning: 1) You **MUST** connect CDL7 to external antenna firstly and then supply power, otherwise the CDL7 will have a risk of burnout; 2) You'd better put it in a shelter when raining, because it's not water-proof.*

● Rover station



- ① A N3 receiver
- ② A Whip antenna
- ③ A controller with software installed
- ④ A range pole with bracket

● Click **Device-> Base ->Add**, select **External radio**.

Datalink Type	
Datalink Type	External radio >
Protocol	Transparent >
Power(W)	30 >
Channel	6 > (00)
Frequency(MHz)	460.0500 +
Range(400-480MHz)	
Air baudrate	9600 >
BaudRate	38400 >
☐ Set CDL3/CDL5 radio Select BaudRate for your External Radio, the other parameters are only work for ComNav CDL5 External Radio.	
Confirm	

- When start succeed, set up the frequency channel, and Rover frequency should be same.
- Be sure to set the same baud rate as your CDL7(default value is 38400, you also can change in **Param tab** based on your CDL7).

5.7 PDA CORS Mode

Without setting up your own base stations, the N3 GNSS receiver can receive correction data transmitted from continuously operating reference station via PDA's GPRS or WIFI. To do RTK survey in PDA CORS mode, it requires:



- ① A N3 receiver
- ② A controller with SIM card and software
- ③ A range pole with bracket

Configure the Rover as below:

- Make sure your controller can access to internet via SIM card or Wi-Fi, then run Survey Master Software.
- Build Bluetooth connection as shown in [chapter 5.4](#), Click **Device** -> **Rover** -> PDA CORS.

Datalink Type

Datalink Type: PDA CORS

Protocol: CORS

APN: SINOGNSS

Server: SINOGNSS

DNS/IP address: 211.144.120.104

Port: 8888

Source List: [Dropdown]

User: [Text Field]

Password: [Text Field]

1021-1022: [Toggle]

1023-1024: [Toggle]

1025-1027: [Toggle]

VRS: [Toggle]

Confirm

- Enter CORS **DNS/IP address** and **port**-> Click **Source List** and select the proper source -> enter **User** and **password**.
- After **Confirm** succeed, the diff LED (yellow) on receiver will flash, and software can get a fixed result.
- It also provides TCP protocol.

5.8 Internal GPRS Mode

For Internal GPRS mode, N3 receiver supports Point to Point/Points and Ntrip client mode. To acquire the APN (access point number) from the mobile service provider, you need to insert a SIM card into the N3 receiver. It commonly acquires the APN from the mobile network provider, otherwise try to get via the link:

http://www.hw-group.com/products/HWq-Ares/HWq-Ares_GSM_APN_en.html#top

5.8.1 Point to Point/Points mode (P to PS mode)

In point to point mode, the correction data is transmitted from the base station to the server, then rovers can log on the server to get the correction data. Therefore, SIM cards are required both in the Base and Rover.

*Tip: ComNav technology provides a free static server address **211.144.120.104:8888**, anyone can upload CORS data as long as abide by the agreement.*

Below shows Base configuration with ComNav server:

- **Server**: select SINOGNSS server(IP: **211.144.120.104** and **Port:8888**)
- **BaseName**: Click BaseName to get SN of Base receiver directly, when start Rover, just select the name as source
- Differential mode: make sure to choose **RTCM32**
- Fix Position: Click **Library choose** to select a known point for the Base, or **Get** from GNSS if you do not have a known point.

The image displays three sequential screenshots of the SinoGNSS N3 Base configuration interface. The first screenshot, titled 'Datalink Type', shows 'Internal GSM' selected for the Datalink Type and 'CORS' for the Protocol. The 'Server' is set to 'SINOGNSS'. The second screenshot, titled 'Base', shows 'SinoGNSS' selected for the Protocol, '211.144.120.104:8888' for the Port, 'RTCM3.2' for the Differential mode, and 'Fix position' for the Start mode. The third screenshot, titled 'FixPosition', shows 'Library choose' selected for the Base station coord... field, with the Name set to 'Base:p0'. The Display type is set to 'Local grid coordinate', and the Antenna type is set to 'T30(NGS)'.

After successfully starting the Base station, the differential LED (yellow) flashes once per second, which means the Base is broadcasting correction data;

Configure the Rover as below:

- Protocol: Select **SINOGNSS** directly;
- BaseName: Enter the SN of the Base receiver.

← Datalink Type

Datalink Type Internal GSM >

Protocol SinoGNSS >

APN CMNET ⚙️

Server SINOGNSS ⋮

DNS/IP address 211.144.120.104

Port 8888

BaseName ⬇️

Confirm

5.8.2 Internal 4G Ntrip client mode

For Ntrip client mode, Rover acquires correction data from Ntrip(CORS) server.

← Datalink Type

Datalink Type Internal GSM >

Protocol CORS >

APN CMNET ⚙️

Server SINOGNSS ⋮

DNS/IP address 211.144.120.104

Port 8888

Source List ⬇️

User sxbhd

Password ✕

VRS ☒

Confirm

- Enter proper **APN, DNS/IP Address and Port.**
- Click **Source List**, select the proper source-> enter User and Password

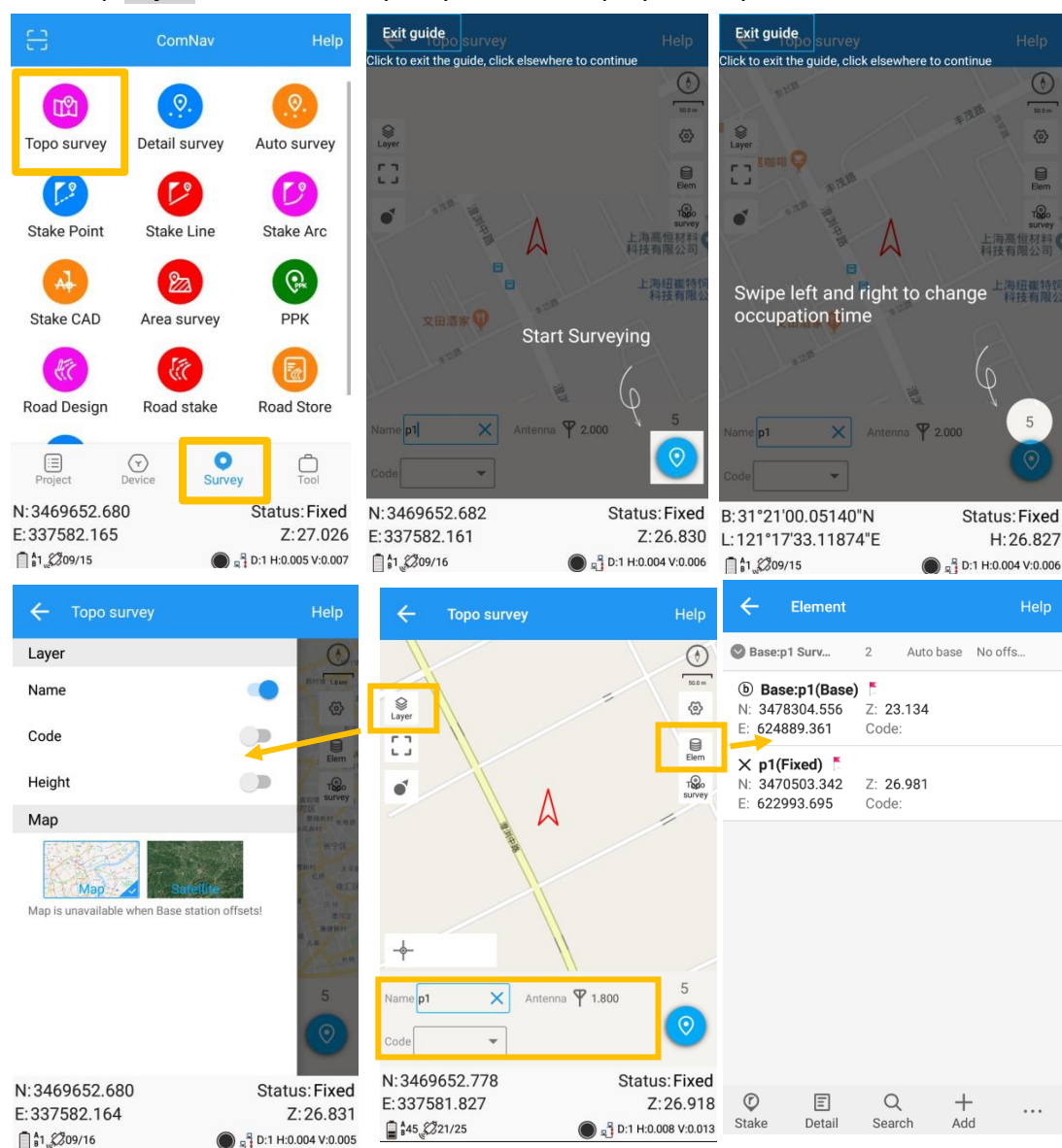
6 Basic Survey Functions

This section describes the basic survey functions of Survey Master, including point measurement, Topo survey, Auto survey, Area survey, Static, PPK, staking, site calibration, import and export measured points.

6.1 Topo survey

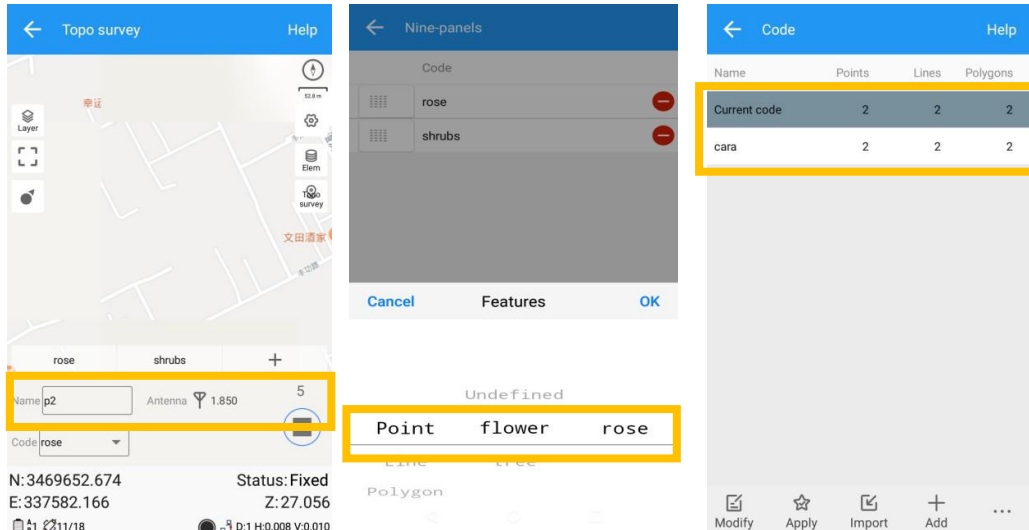
Click Topo Survey-> enter point name, ->click  to start or stop collecting data.

- You can quickly change antenna height in the survey interface.
- Tap **Elem** to check point coordinates.
- Tap **Layer** to show the layers you want display on map.

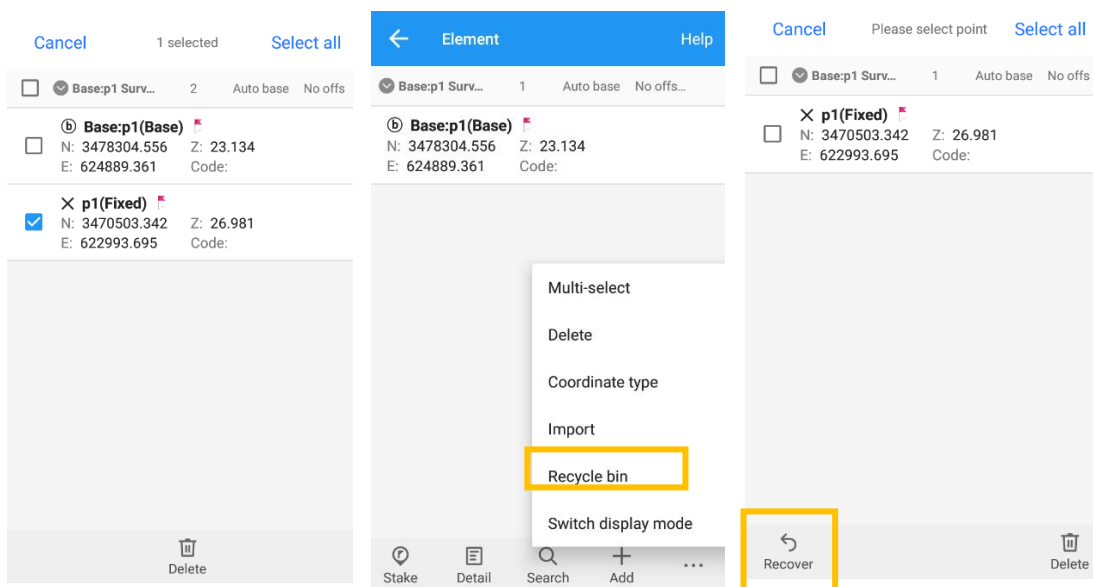


- Fast survey by pressing Code: Tap the code in nine panels, will survey the point directly.

Go into code management interface to modify code list, then you can choose code to use in nine panels.



- Recover deleted points in Recycle Bin.



6.1.1 Survey settings

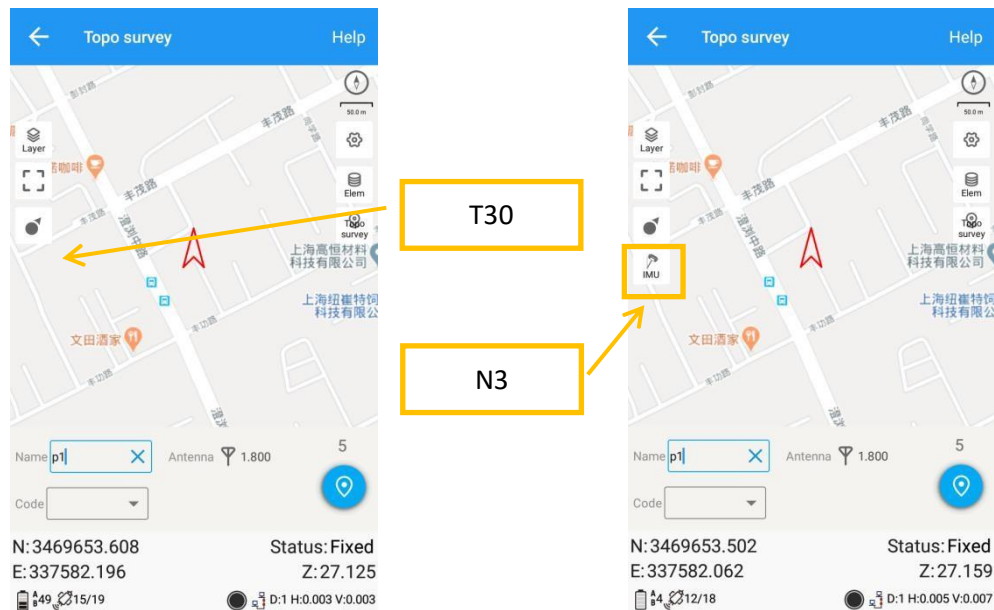
- Fixed: only fixed result can be saved;
- Duplicate name: allow point name same;
- RMS: point accuracy need higher than the value;
- Offset radius: point cannot offset bigger than the value during measure;
- Occupation time: measure times for one point;
- Point stepsize: for point name;
- Stake range: show circle when close to target point;

- Direction guide: 3 methods showing guide for stake out;
- Electronic compass: Use controller compass during stake out;
- Auto centered: Map will go to current location after 5 seconds;
- Keep centered: Map will go to current location after 1 second;
- Display survey points: will show all survey points on map;
- Display Basemap: for showing DXF/SHP file on map

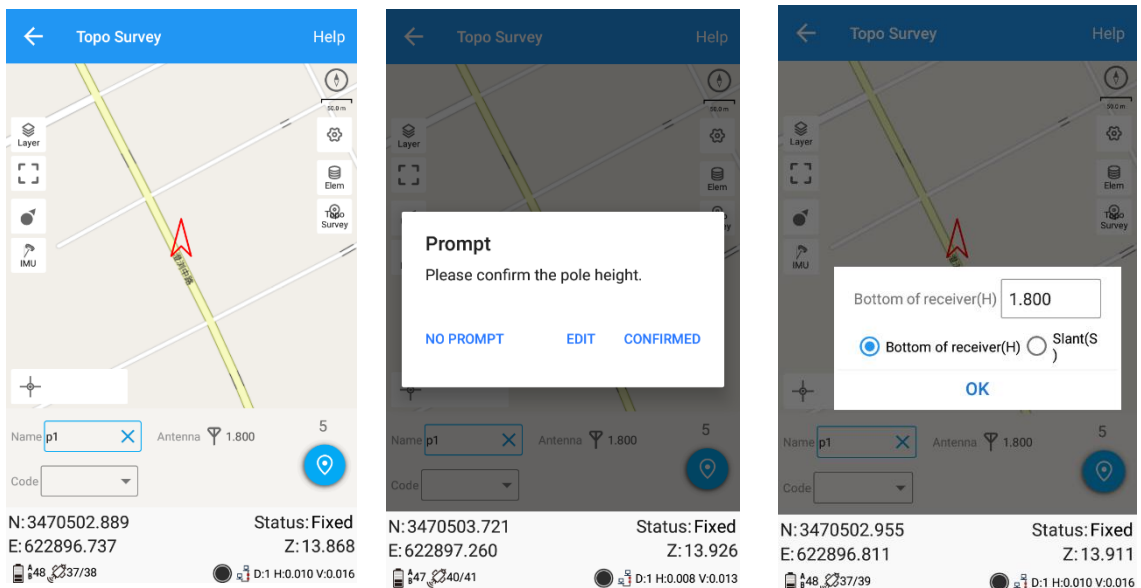
6.1.2 Tilt survey

Tilt survey option will appear when receiver supports for tilt survey, it is available for ComNav Technology N3 GNSS receiver, use IMU sensor.

According to the IMU sensor, can not only meets the requirement of high precision measurement, but also relieves the users from continually checking whether the pole is plumb. When the pole tilts within 60° , the built-in sensor based IMU precisely calculates the actual offset, which accuracy can up to 2.5 cm



1. Open IMU: Go into Topo survey—click the button to open.



After you click IMU button, it will give you one prompt to check the antenna information.

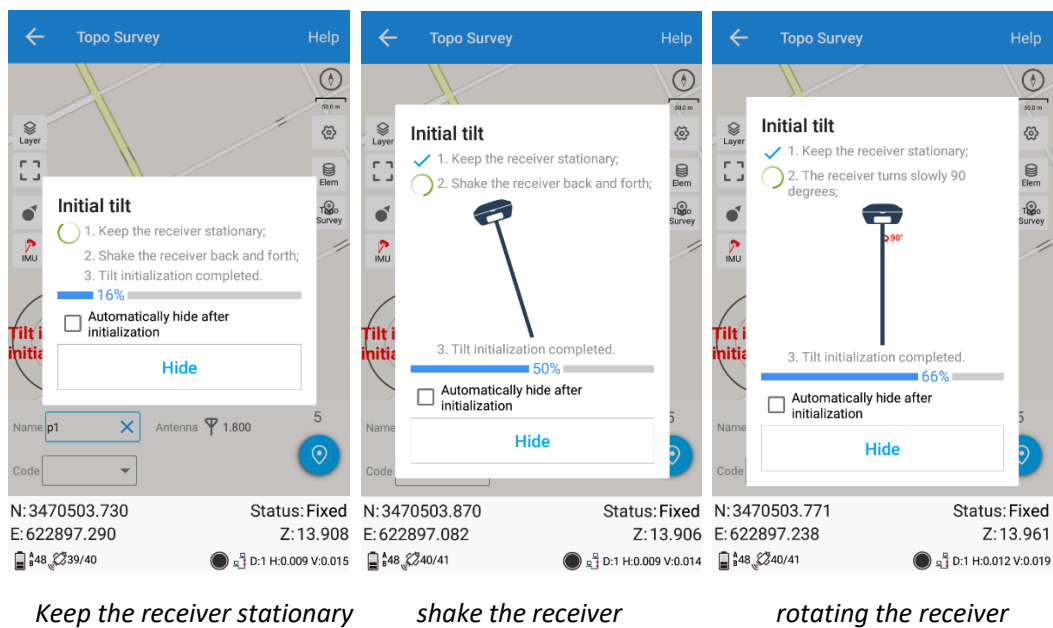
Edit: Change the antenna information.

Confirmed: You have been confirmed the antenna information, and it is correct.

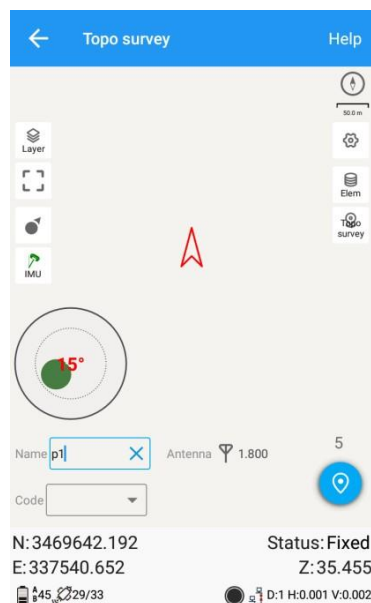
NO PROMPT: will not give this prompt next time when you do IMU calibration.

2. Initialization

If you power off the receiver or freset it, need to initialize again. After open IMU button, you can follow the guidance in interface to complete it. During operation, make receiver can search the satellites and get a fixed solution.



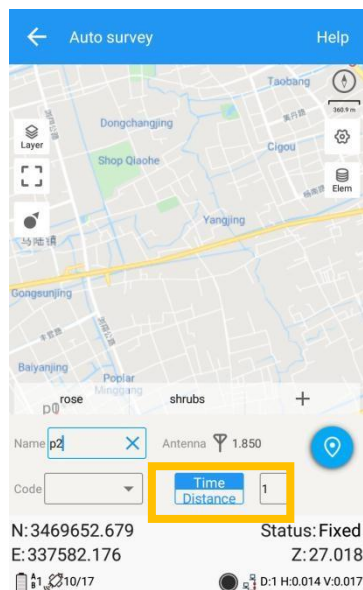
In survey interface, you can find the bubble and angle value shows the pole you tilt. For more accuracy, angle less than 60° will be better.



Tip: Do not shake or rotate the receiver violently, otherwise you need to re-initialize.

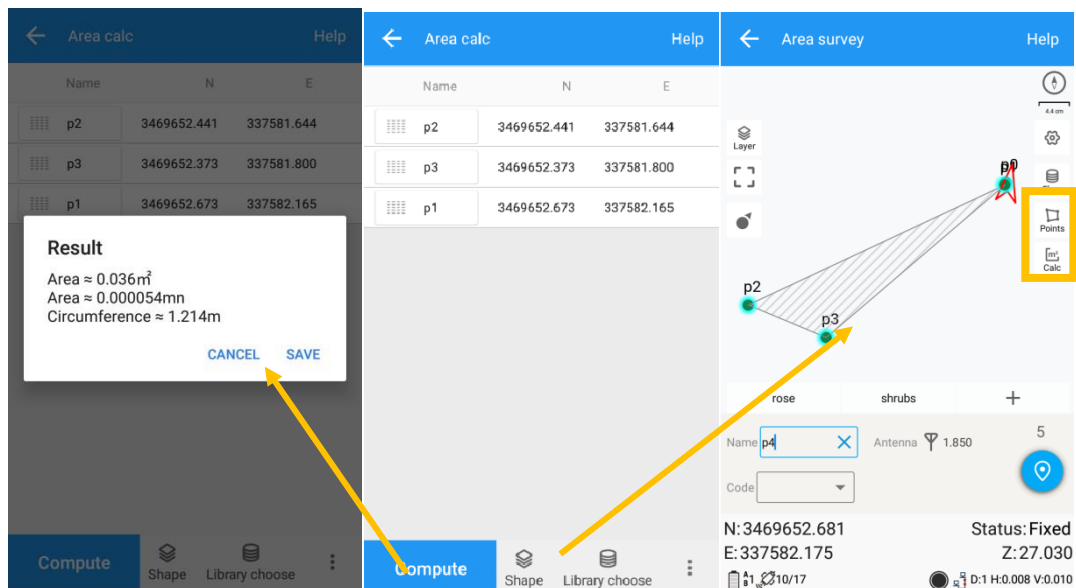
6.2 Auto survey/Area survey

For Auto survey, it supports automatic and continuous survey according to Time or Distance.



For Area survey, it can compute area directly after getting points.

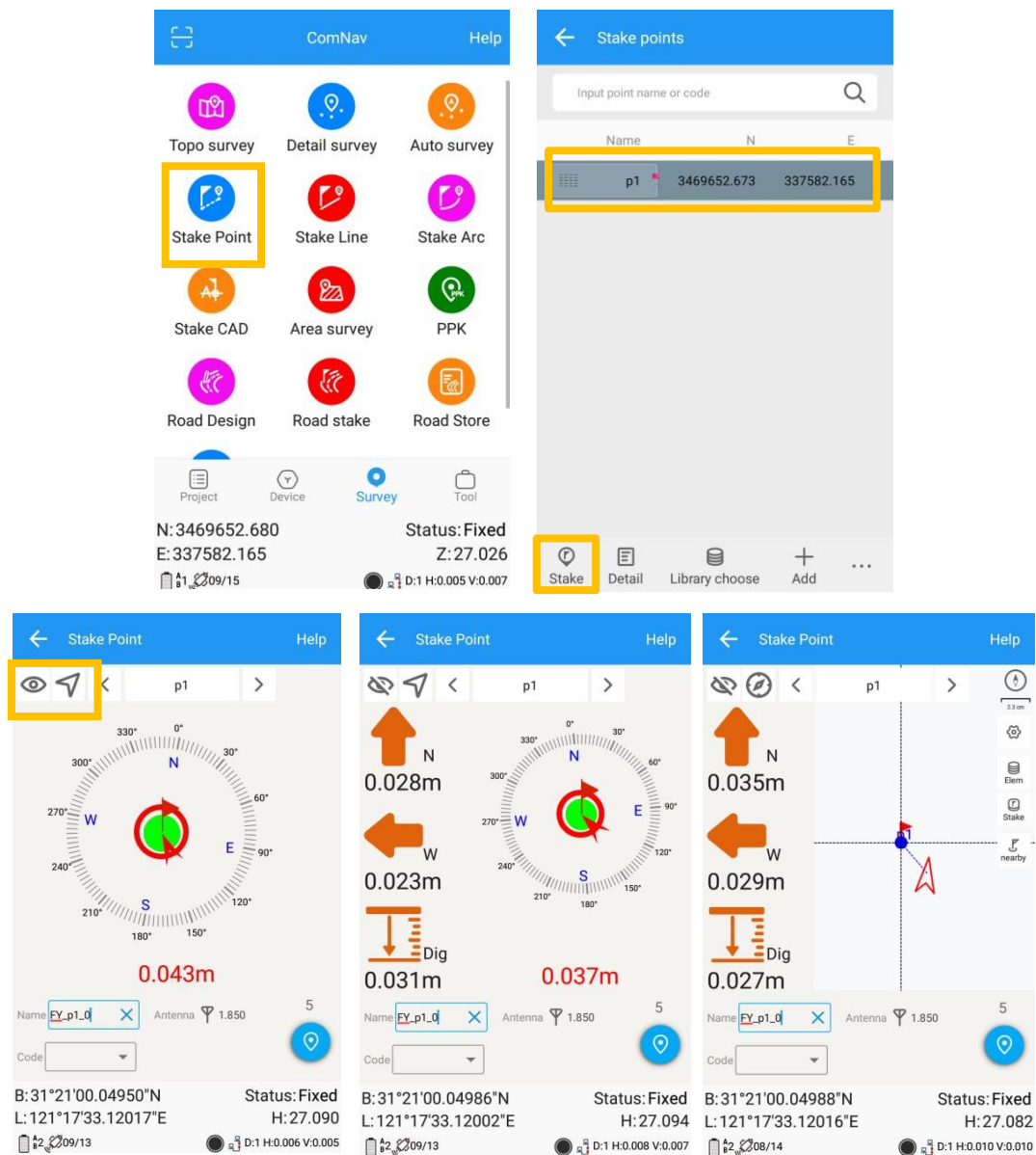
Press , it will show the coordinate information, press , it will show the area result, press , it will show the shape on map.



6.3 Stake points/lines

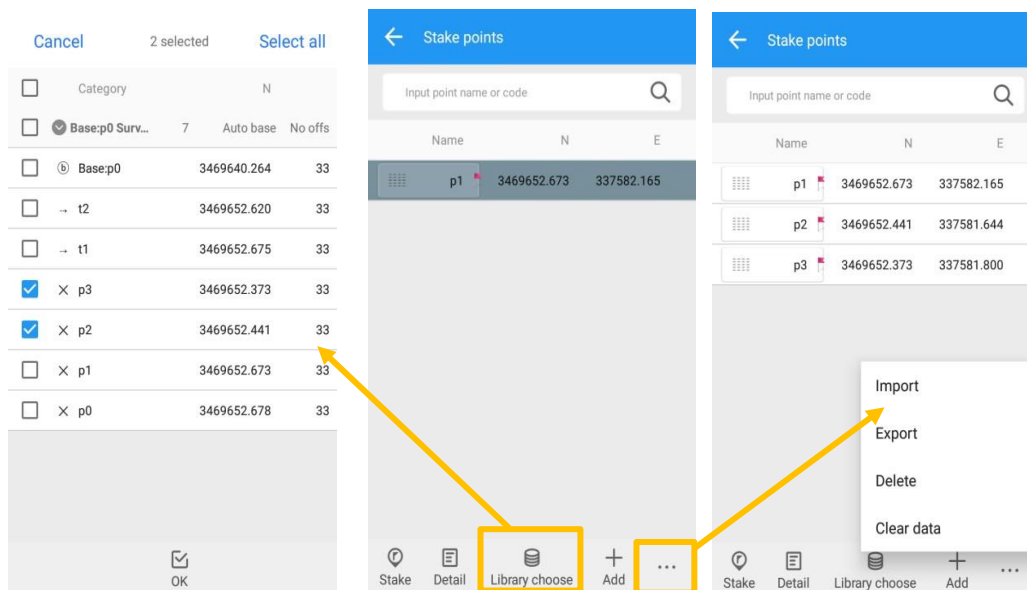
Go into **Stake point** interface, click to choose a point and tap **Stake**. Survey Master provides a navigation map when staking points/lines. If you are close to the target point enough, it will alarm you based on the alarm range you set.

Enter the point name and code based on your requirements, then click 



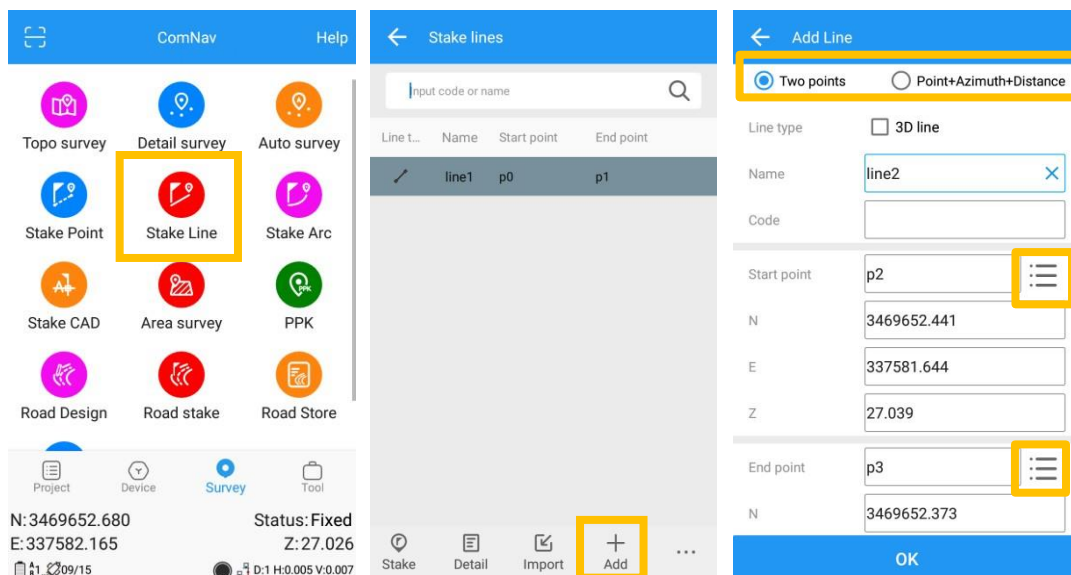
Various navigation info choices

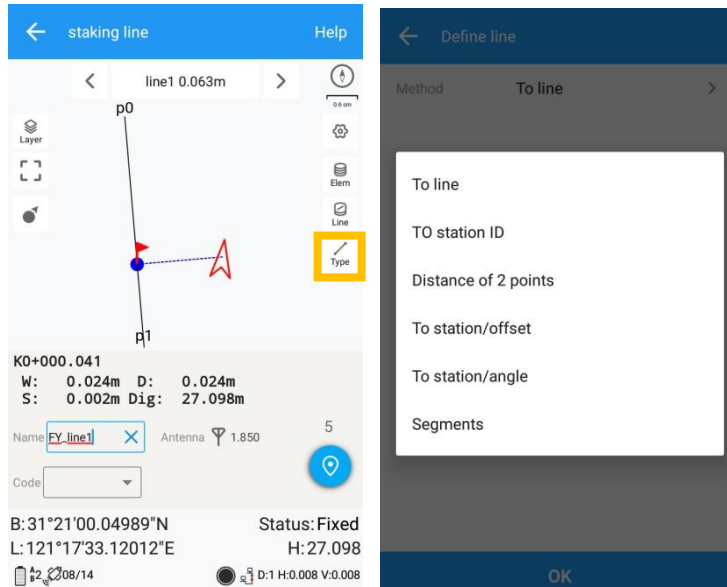
You can also **Import** points for staking, or add from **Library choose**.



Tip: keep your receiver vertical to the ground.

For staking lines, click  add line (Two points or Point + Azimuth + Distance) -> click  -> Choose one line and click Stake. The default method to stake is “To line”, press method to choose a method you want.





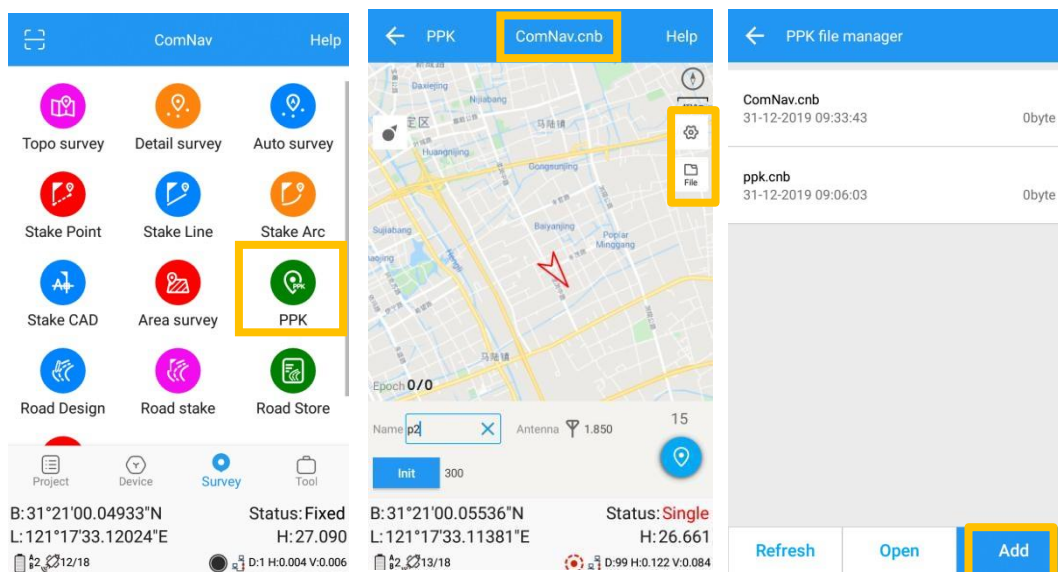
- To line: show shortest way to find a point on line;
- To station ID: stake points on line by defined interval;
- Distance of 2 points: show distance of current location to the line's start point and end point;
- Segment: Stake on line by defined segment value.

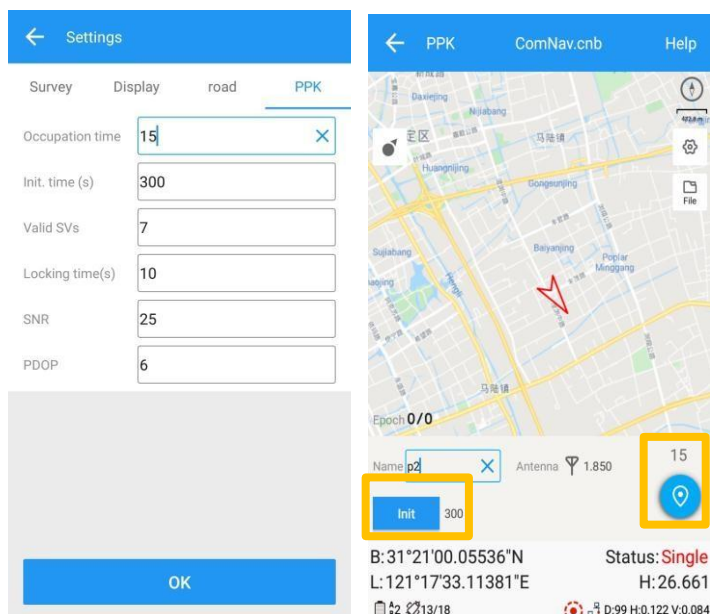
6.4 PPK

PPK (post processing kinetic) is the unique function of survey master, which is used for post-processing dynamic measurements.

It also needs two receivers to work together, one work as Base to record static data, and another one work as Rover as shown below.

1. Click PPK in survey interface -> choose or create a PPK file.
2. Go to settings, configure PPK settings based on your requirements.
3. To get stable epoch, click **Init** to initialize -> to start PPK survey.



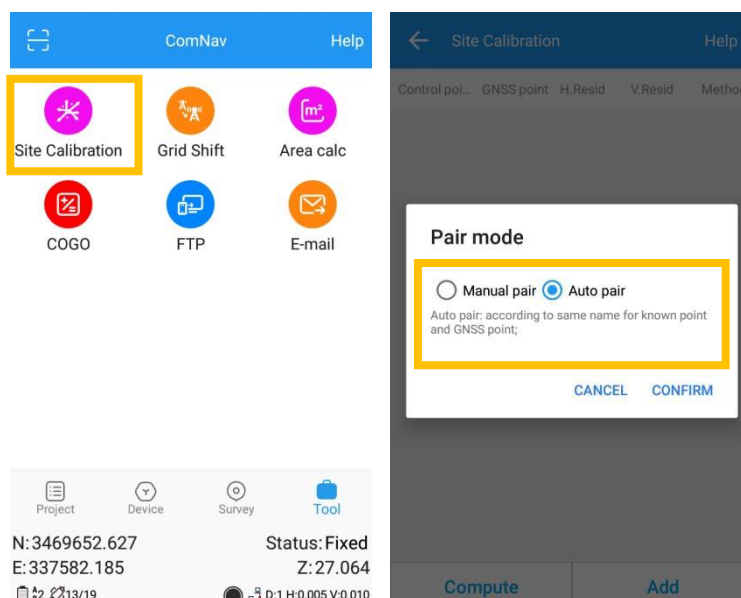


6.5 Site calibration/Grid Shift

6.5.1 Site calibration

Site calibration is commonly needed once in one project, and all the points will be collected based on calibrated datum system.

1. Choose manual pair or auto pair.



2. If you choose Calibration manual pair, you can directly enter at least three groups' point to compute. (for example, take K1,K2,K3 as known points, take A1,A2,A3 as measured points) After click **Compute** to calculate, the software will calibrate

automatically.

**Click to add
K1, K2, K3**

**Click to add
A1, A2, A3**

← Edit

Control point

Name

N

E

Z

GNSS point

Name

B

L

H

OK

← Site Calibration Help

Control poi...	GNSS point	H.Resid	V.Resid	Method
K1	A1			H.&V.
K2	A2			H.&V.
K3	A3			H.&V.

Compute Add

← Site Calibration Help

Control poi...	GNSS point	H.Resid	V.Resid	Method
K1	A1	0.022	0.000	H.&V.
K2	A2	0.062	0.000	H.&V.
K3	A3	0.075	0.000	H.&V.

Succeed for horizontal calibration!
Succeed for vertical calibration!

Apply Add

3. If you choose auto pair, it will auto compute according to the same name for known point and measured point. After click **Compute** to calculate, the software will calibrate automatically.

← Edit

Control point

Name

N

E

Z

GNSS point

Name

B

L

H

OK

← Site Calibration Help

Control poi...	GNSS point	H.Resid	V.Resid	Method
K3	K3			H.&V.
K2	K2			H.&V.
K1	K1			H.&V.

Compute Add

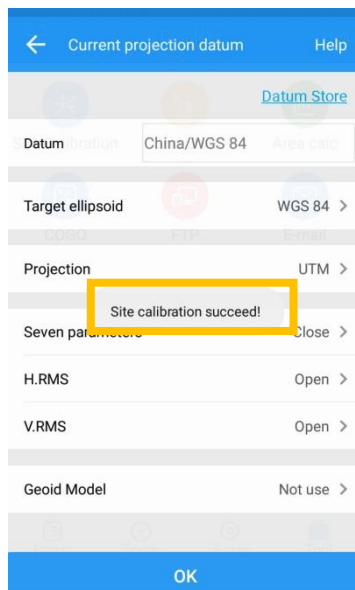
← Site Calibration Help

Control poi...	GNSS point	H.Resid	V.Resid	Method
K3	K3	0.075	0.000	H.&V.
K2	K2	0.062	0.000	H.&V.
K1	K1	0.022	0.000	H.&V.

Succeed for horizontal calibration!
Succeed for vertical calibration!

Apply Add

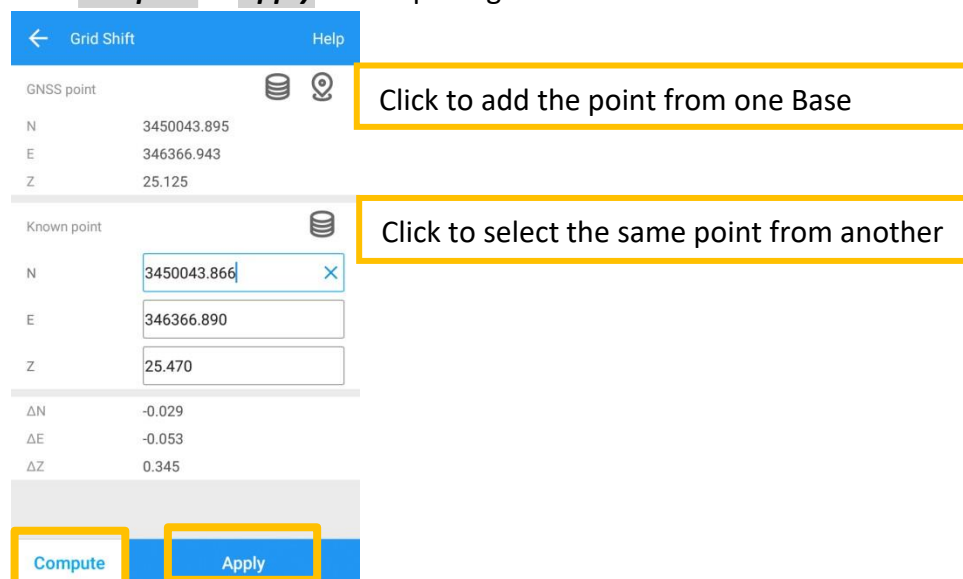
4. Click **Apply** to confirm to replace datum. The value of H.Resid and V.Resid should meet the requirement ($H.Resid \leq 0.015m$, and $V.Resid \leq 0.02m$).



6.5.2 Grid Shift

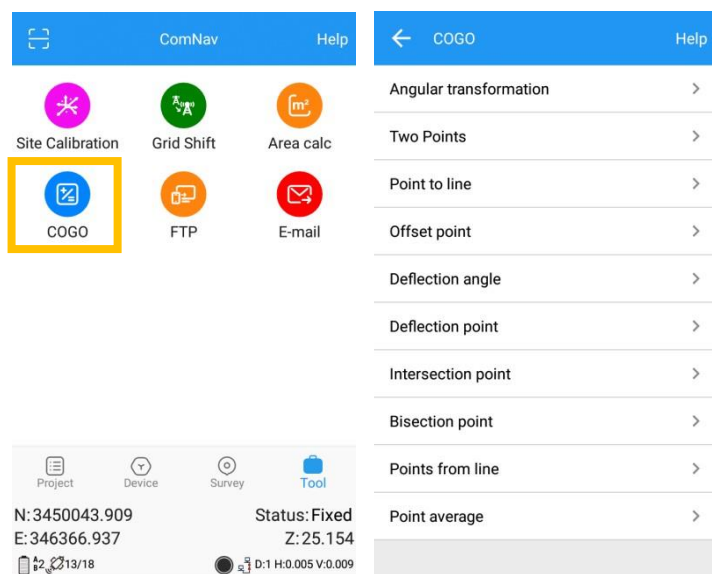
Grid reset function is applied when you need to change the position of Base station in the same project.

Click **Grid Shift** in Survey interface -> add current Base point and target Base point -> Click **Compute** -> **Apply** to complete grid shift.



6.6 COGO

With COGO function, you can calculate points/lines/angle directly on field.



- Angular transformation: Angular type transform;
- Two points: Calculate two points distance;
- Point to line: Distance from point to one line;
- Offset point: Calculate point with azimuth and distance;
- Deflection angle: Calculate angle of two lines;
- Deflection point: Calculate point with angle and distance;
- Intersection point: Calculate intersection points from two lines;
- Bisection point: Calculate point from angle bisector;
- Points from line: Calculate points on line by distance or segment;
- Point average: Calculate average from points;

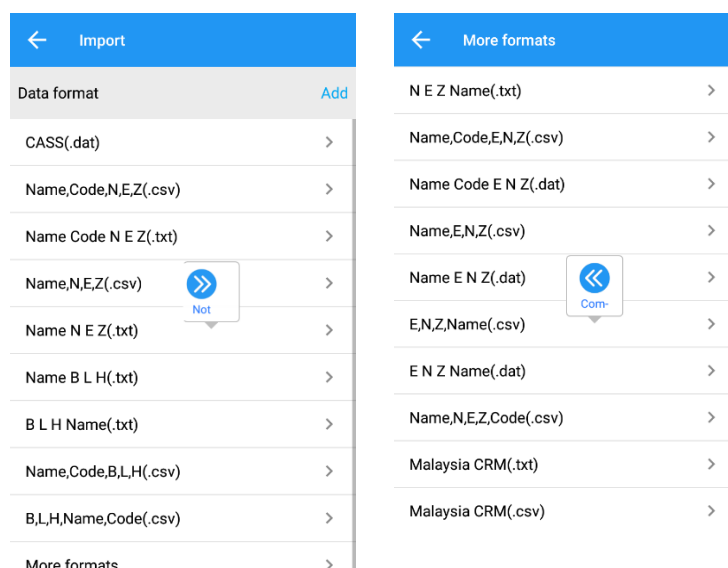
7 Data Export/Import

Survey Master supports to import/export data including grid coordinate, Lat/Lon coordinate with various data format, support import DXF/DWG file and export result of DXF/KML, etc.

7.1 Import

Tap **Import** in project interface, there are some predefined data formats, click **More formats** to get more predefined formats. Besides, you can click **Add** to create a User-defined type.

Long press the predefined data format that you don't use often, you can move this format to the More formats page; also, you can move the data format of More formats page to the previous page where stored the formats you usually use.



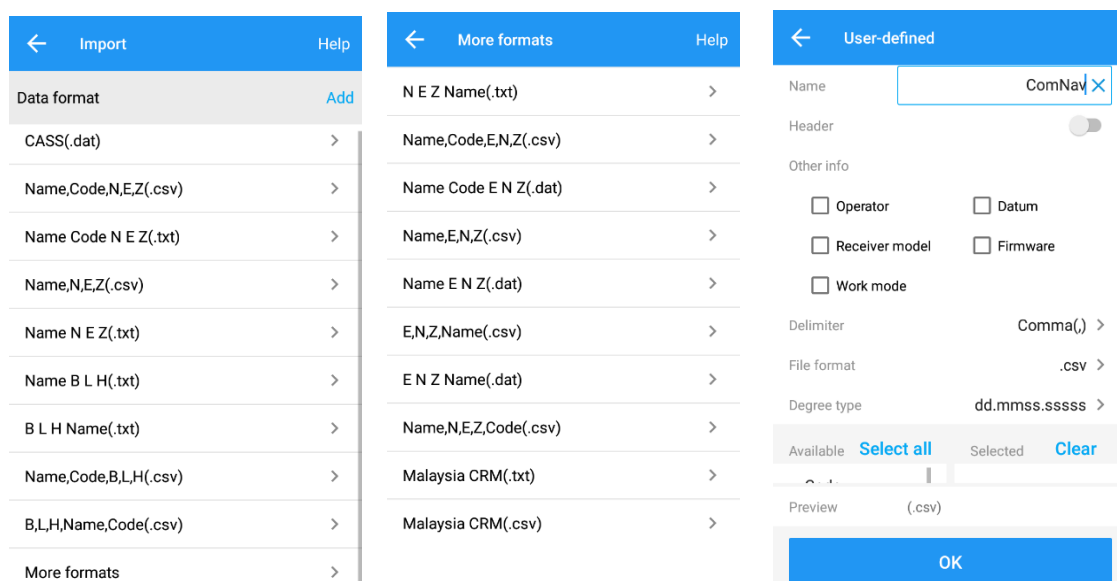
- Name: Enter the name for the format
 - Delimiter: support Comma(,), Space(), Semicolon(;
 - File format: support *.csv, *.dat, *.txt format
- Click **Select all** to choose all elements, Click **Clear** to eliminate all elements selected.

The elements include: code, name, N, E, Z, B, L, H, X RMS, Y RMS, V.RMS, status, start time, occupation time, diff age, base ID, total AntHgt, Antenna height, measure type, antenna name, ending time, comment, RMS, PDOP, HDOP, VDOP, TDOP, GDOP, total SV, used SV, elevation, tilt offset, tilt angle, tilt distance

Tip: The format you defined will also be saved to Export interface.

Choose one format to import data.

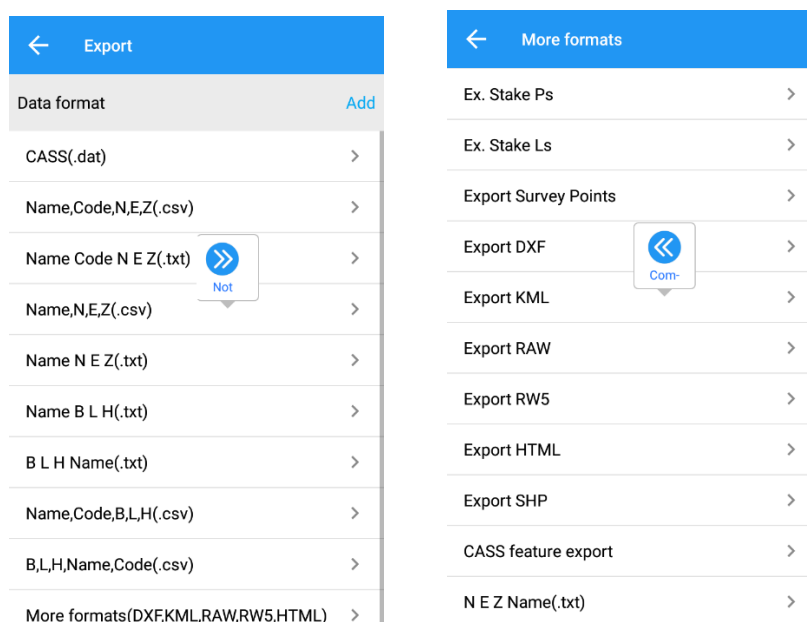
- The default export path is `.../Sinognss/sm/data`, you can also click **Upper folder** to change to any other path where the file is.
- Point type: support Input point, Control point, Stake point



7.2 Export

Tap **Export** in Project interface to export simple data of survey points. Also, click **More formats** to export the survey points with detailed information or other formats like stake points/lines, DXF, SHP, KML, RAW, RW5, HTML, CASS feature result.

Same with Import result, long press the predefined data format to select the interface you want to place.

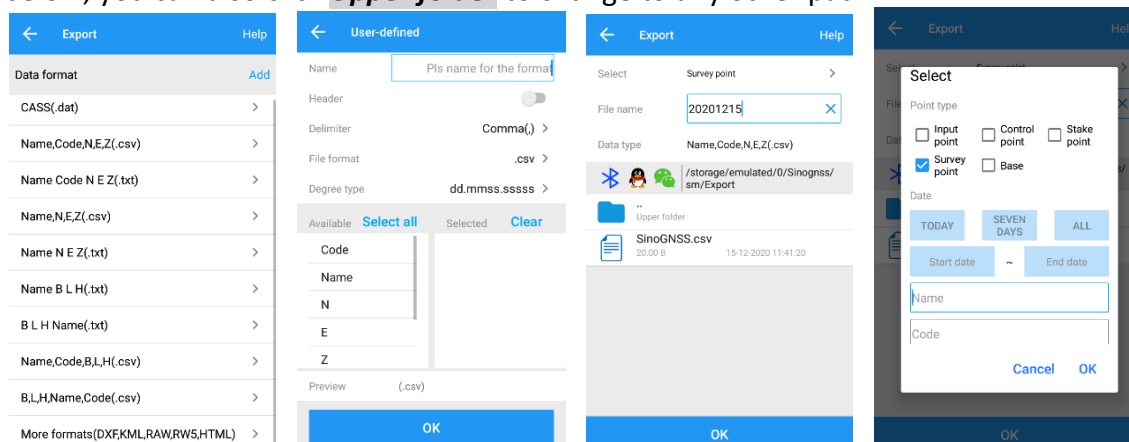


- File format: support *.csv, *.dat, *.txt format

Choose one format to export data.

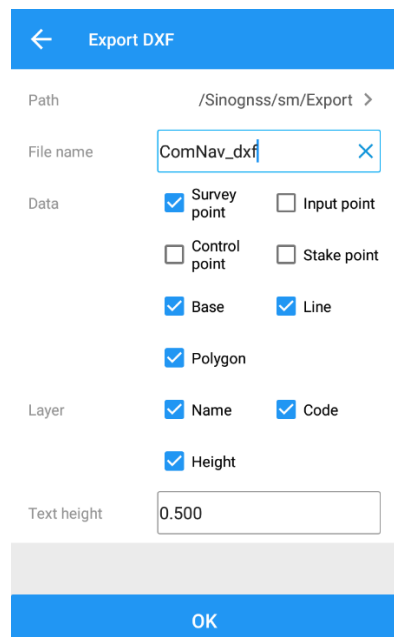
- Select: support Survey point, Control point, Input point, Stake point, Base, also, you can set the date, name, code of data to specific export

The default export path is `.../Sinognss/sm/export`, and the previous saved file will be shown below, you can also click **Upper folder** to change to any other path.



For the points, lines and polygons you surveyed in Topo survey and Feature survey, you can click **Export DXF** to export dxf file, then you can edit them in third party CAD software, or import to **Basemap** to check, or import to **Stake CAD** to stake.

Choose the data that you want to export including survey point, input point, control point, stake point, base, line and polygon, and the layer properties includes name, code and height, the default text height is 0.5.



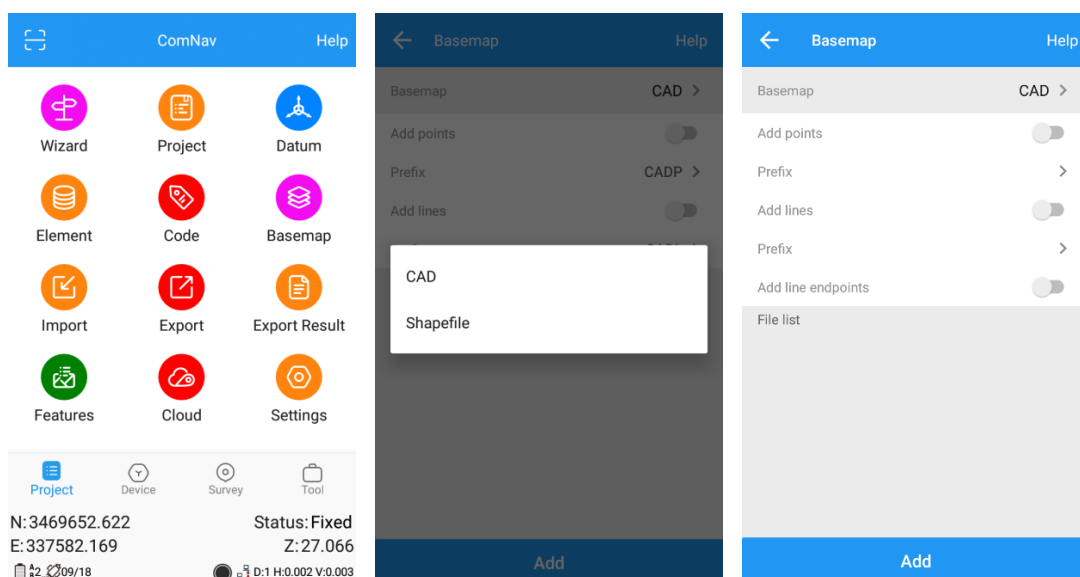
The 'Export DXF' dialog box is shown with the following fields and options:

- Path:** /Sinognss/sm/Export >
- File name:** ComNav_dxf
- Data:**
 - ☒ Survey point, ☐ Input point
 - ☐ Control point, ☐ Stake point
 - ☒ Base, ☒ Line
 - ☒ Polygon
- Layer:**
 - ☒ Name, ☒ Code
 - ☒ Height
- Text height:** 0.500
- Buttons:** OK

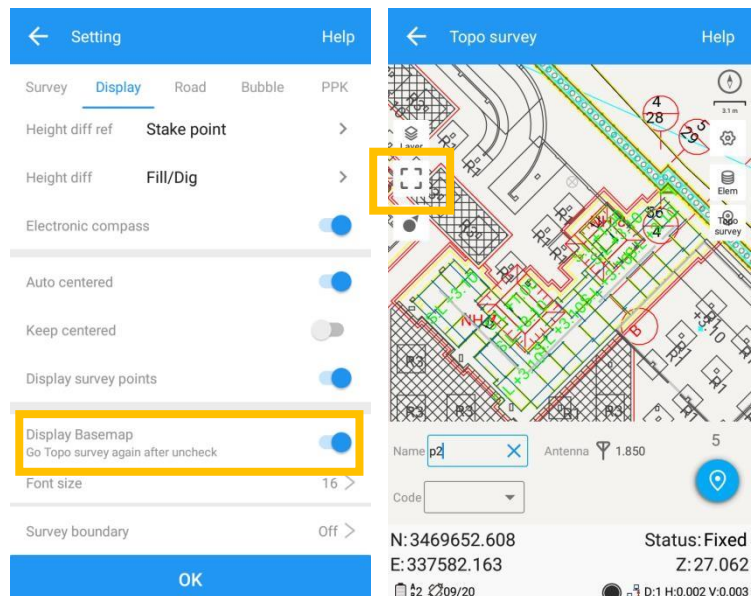
7.3 Import Basemap

Tap **Basemap** to import DXF/DWG/SHP file into Survey Master.

- Add points: Save points from the dxf/dwg/shp file to element.
- Add lines: Save lines from the dxf/dwg/shp file to element.
- Prefix: Support add prefix name for points/lines saved to Elements.
- Add line endpoints: add line endpoints to point element.



Remember go survey settings to check on display basemap, click zoom button to auto show basemap.

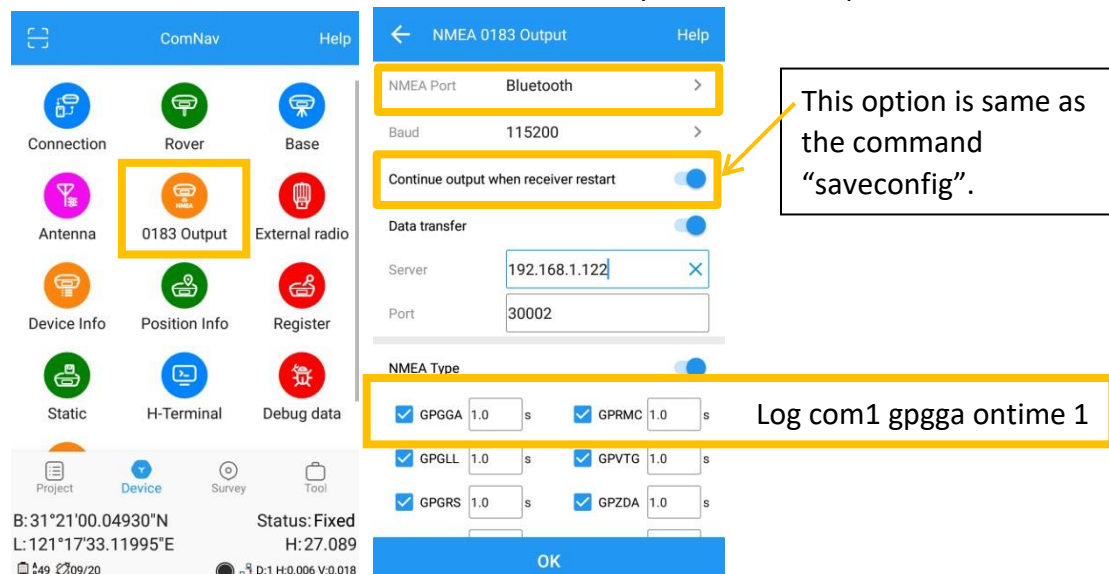


8 Export Result

8.1 NMEA 0183 output

With **NMEA 0183** function, you can quickly set to output NMEA data from lemo port or Bluetooth. In fact, this function is same as enter commands “log comX gpXXX ontime X”.

Choose NMEA Port -> Baud -> check commands you want to output.



Data transfer: for transmit all the BT output to the address.

8.2 Register N3 via Survey Master

Normally, the register code is like this:

ID:03401012 \$\$:49-0B-79-23-00-00-00-95-85

FUNCTIONREG:2207453726-3851620954-0949162572-0697504466-0613618189-0027539229

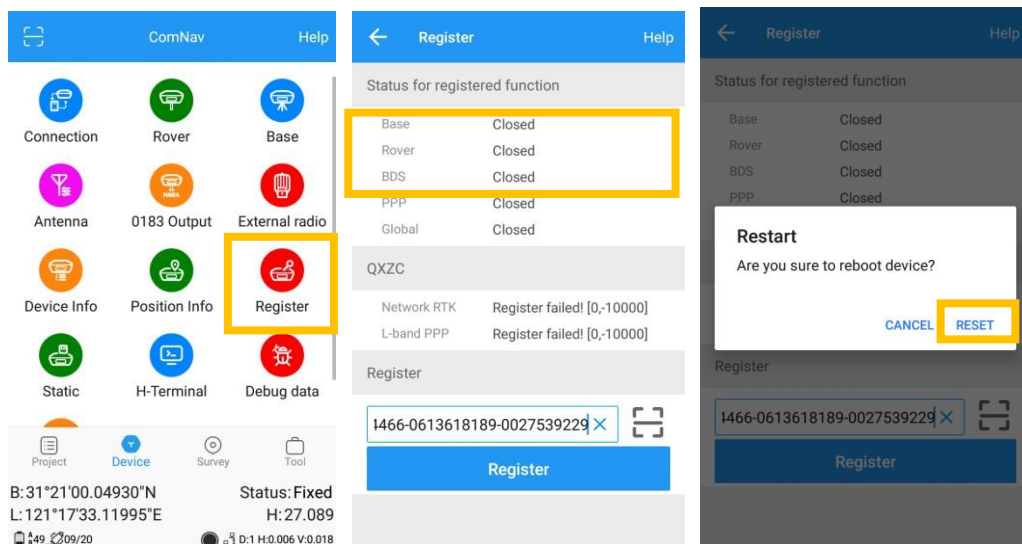
Note: The length of code may different according to different requirements.

Following shows two methods to register the receiver.

➤ Register function

For Register function, you need only enter the number:

2207453726-3851620954-0949162572-0697504466-0613618189-0027539229



➤ Register via commands

You need copy the whole code, include the word 'FUNCTIONREG:'

FUNCTIONREG:2207453726-3851620954-0949162572-0697504466-0613618189-0027539229

Copy the whole code, and enter the cursor to next line, then send.

Send command: LOG REGLIST
To check receiver register status.

Valid Registered Function Number: 5.
Function: HEADING Expired time:2020-07-03
Function: BD2SIGNAL Expired time:2020-07-03
Function: ROVER Expired time:2020-07-03
Function: BASE Expired time:2020-07-03
Function: RAWMSG Expired time:2020-07-03

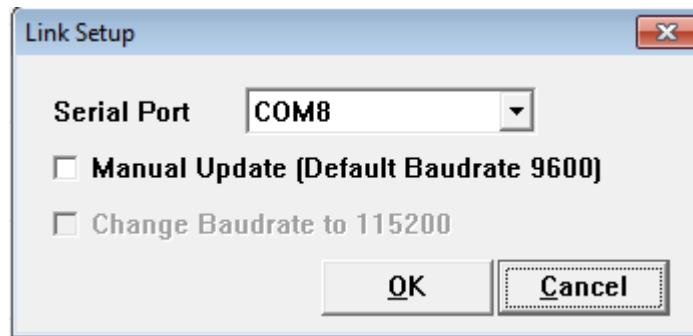
Current Function Status:
Function: 20HZOBS Usable: NO
Function: GNSSL3 Usable: YES
Function: HEADING Usable: YES
Function: GLOSIGNAL Usable: YES
Function: BD2SIGNAL Usable: YES
Function: GALSIGNAL Usable: YES
Function: GNSSL2 Usable: YES
Function: ROVER Usable: YES
Function: BASE Usable: YES
Function: DYNAMIC Usable: NO
Function: B3DIRACQ Usable: NO
Function: B3PRC Usable: NO
Function: SLTISOFTID Usable: YES
Function: RAWMSG Usable: YES
Function: EXTCOORDREF Usable: NO
Function: ZONEGLOBAL Usable: NO
Function: GPSSIGNAL Usable: YES
Function: INNERRADIO Usable: YES
Function: COMMONVIEW Usable: NO
Function: SPACESCENE Usable: NO

log reglist

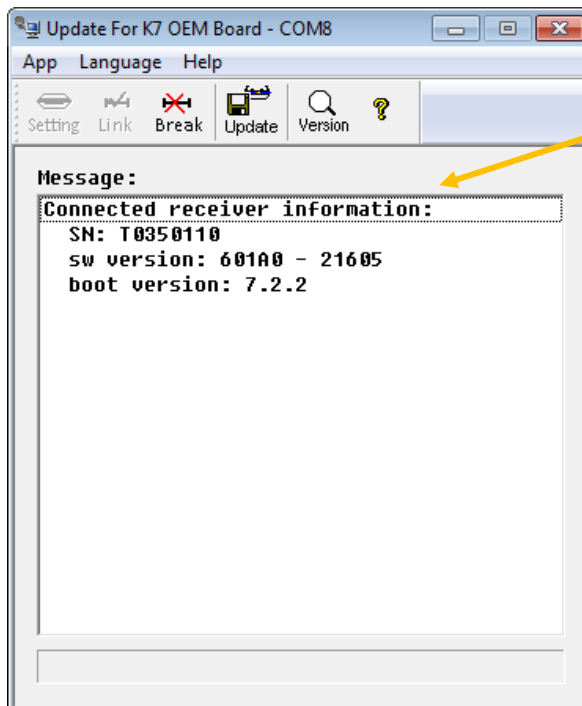
9 Firmware Upgrade

Prepare a Lemo to serial port cable.

1. Copy the firmware software to your PC, connect N3 to your PC via serial port cable and turn on the receiver.
2. Open the firmware program, choose "APP->Link setup", select **proper port** to connect with receiver, and then click "OK".



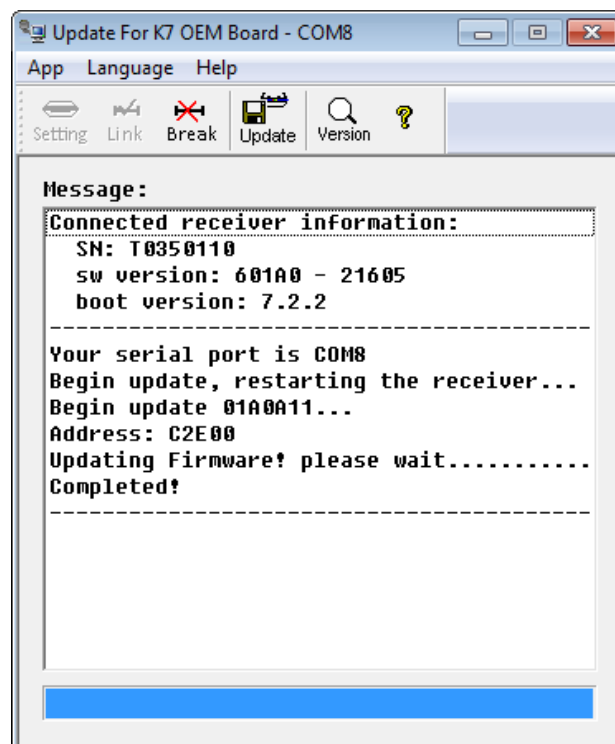
3. Click “**Link**” icon to build the connection (this is important to check if the N3 is connect to PC successful)



If output this receiver information means it connection correctly

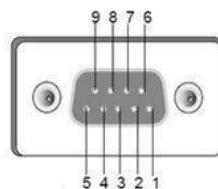
Then click “**Update**” icon to start the update (a few seconds are needed), during update, the N3 will restart automatically and all LEDs on N3 should be on.

When the progress bar is full, and “**Completed!**” appear below, it seems the update has been completed and then you can click “**Break**” to finish the update.

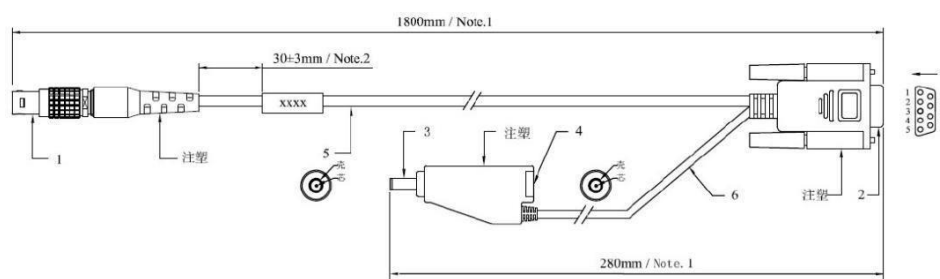


Appendix A: 7-Pin Lemo definition

The following figures show the definition of 7-pin lemo, and the structure of 7-pin Lemo to RS232 Cable:



7 pin Lemo	Description
1	Signal GND
2	GND
3	TX data out (TXD)
4	NONE
5	NONE
6	Power In (+)
7	Serial data in (RXD)



Appendix B: Physical Parameter of Modules inside of N3

➤ **Radio:**

Radio parameter	Specifications
Frequency range	410.0250-469.9750MHz
Airlink rate	9600 bps
Bandwidth	25kbps
Power	0.5, 1, 2 Watt adjustable
Work distance	10-15km, depends on power supply and environment condition
Modulation	GMSK

➤ **Bluetooth:**

- Frequency Range: 2.402Ghz-2.480Ghz
- RF Power (Max): 4dBm
- Band Width: 2Mhz